

1 Problem 4.9

1.1

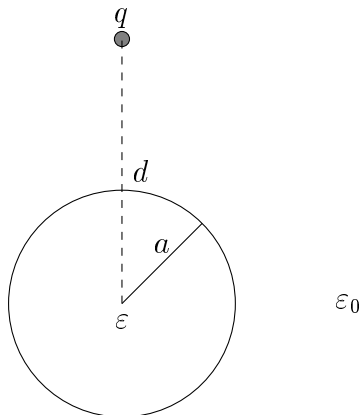


Figure 1: Setup for problem 4.9

Using the fact that we have azimuthal symmetry, we have inside the sphere:

$$\Phi_{\text{in}}(\vec{r}) = \sum_{l=0}^{\infty} A_l r^l P_l(\cos \theta) \quad (1)$$

And outside the sphere:

$$\Phi_{\text{out}}(\vec{r}) = \Phi_q + \sum_{l=0}^{\infty} B_l r^{-(l+1)} P_l(\cos \theta)$$

where Φ_q is the potential due to the charge q .

$$\Phi_q = \frac{q}{4\pi\epsilon_0} \frac{1}{|\vec{r}' - \vec{r}|} = \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \frac{r_{<}^l}{r_{>}^{l+1}} P_l(\cos \gamma)$$

Because r' only points to the single point charge along the z -axis, $\gamma = \theta$. Therefore:

$$\Phi_{\text{out}}(\vec{r}) = \sum_{l=0}^{\infty} \left(\frac{q}{4\pi\epsilon_0} \frac{r_{<}^l}{r_{>}^{l+1}} + B_l r^{-(l+1)} \right) P_l(\cos \theta) \quad (2)$$

Now, we need to apply the following boundary conditions:

$$-\frac{1}{a} \frac{\partial \Phi_{\text{in}}}{\partial \theta} \Big|_{r=a} = -\frac{1}{a} \frac{\partial \Phi_{\text{out}}}{\partial \theta} \Big|_{r=a} \quad (3)$$

$$-\epsilon \frac{\partial \Phi_{\text{in}}}{\partial r} \Big|_{r=a} = -\epsilon_0 \frac{\partial \Phi_{\text{out}}}{\partial r} \Big|_{r=a} \quad (4)$$

Applying equation (3) yields:

$$\begin{aligned}
-\frac{1}{a} \sum_{l=0}^{\infty} A_l r^l \dot{P}_l(\cos \theta)(-\sin \theta) \Big|_{r=a} &= -\frac{1}{a} \sum_{l=0}^{\infty} \left(\frac{q}{4\pi\epsilon_0} \frac{r^l}{r^{l+1}} + B_l r^{-(l+1)} \right) \dot{P}_l(\cos \theta)(-\sin \theta) \Big|_{r=a} \\
\sum_{l=0}^{\infty} A_l a^l &= \sum_{l=0}^{\infty} \left(\frac{q}{4\pi\epsilon_0} \frac{a^l}{d^{l+1}} + B_l a^{-(l+1)} \right) \\
A_l &= \frac{q}{4\pi\epsilon_0} d^{-(l+1)} + B_l a^{-(2l+1)} \tag{5}
\end{aligned}$$

Applying equation (4) yields:

$$\begin{aligned}
-\varepsilon \sum_{l=0}^{\infty} A_l l r^{l-1} P_l(\cos \theta) \Big|_{r=a} &= -\varepsilon_0 \sum_{l=0}^{\infty} \left(\frac{q}{4\pi\epsilon_0} \frac{l r^{l-1}}{d^{l+1}} + B_l (-l-1) r^{-(l+2)} \right) P_l(\cos \theta) \Big|_{r=a} \\
\varepsilon \sum_{l=0}^{\infty} A_l l a^{l-1} &= \varepsilon_0 \sum_{l=0}^{\infty} \left(\frac{q}{4\pi\epsilon_0} \frac{l a^{l-1}}{d^{l+1}} + B_l (-l-1) a^{-(l+2)} \right) \\
A_l &= \frac{q}{4\pi\varepsilon} d^{-(l+1)} - \frac{\varepsilon_0}{\varepsilon} B_l \frac{l+1}{l} a^{-(2l+1)} \tag{6}
\end{aligned}$$

Equating equations (5) and (6):

$$\begin{aligned}
\frac{q}{4\pi\varepsilon_0} d^{-(l+1)} + B_l a^{-(2l+1)} &= \frac{q}{4\pi\varepsilon} d^{-(l+1)} - \frac{\varepsilon_0}{\varepsilon} B_l \frac{l+1}{l} a^{-(2l+1)} \\
B_l a^{-(2l+1)} \left(1 + \frac{\varepsilon_0}{\varepsilon} \frac{l+1}{l} \right) &= \frac{q}{4\pi} d^{-(l+1)} \left(\frac{1}{\varepsilon} - \frac{1}{\varepsilon_0} \right) \\
B_l &= \frac{q}{4\pi\varepsilon_0} \frac{a^{2l+1}}{d^{l+1}} \frac{\left(\frac{\varepsilon_0}{\varepsilon} - 1 \right) l}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)}
\end{aligned}$$

Plugging B_l into equation (5):

$$\begin{aligned}
A_l &= \frac{q}{4\pi\varepsilon_0} d^{-(l+1)} + \frac{q}{4\pi\varepsilon_0} d^{-(l+1)} \frac{\left(\frac{\varepsilon_0}{\varepsilon} - 1 \right) l}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)} \\
A_l &= \frac{q}{4\pi\varepsilon_0} d^{-(l+1)} \left[1 + \frac{\left(\frac{\varepsilon_0}{\varepsilon} - 1 \right) l}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)} \right] \\
A_l &= \frac{q}{4\pi\varepsilon} d^{-(l+1)} \frac{2l+1}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)}
\end{aligned}$$

Plugging these expressions for A_l and B_l into equations (1) and (2):

$$\begin{aligned}
\Phi_{\text{in}}(\vec{r}) &= \frac{q}{4\pi\varepsilon d} \sum_{l=0}^{\infty} \left(\frac{r}{d} \right)^l \frac{2l+1}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)} P_l(\cos \theta) \\
\Phi_{\text{out}}(\vec{r}) &= \frac{q}{4\pi\varepsilon_0} \sum_{l=0}^{\infty} \left(\frac{r^l}{r^{l+1}} + \frac{a^{2l+1}}{(rd)^{l+1}} \frac{\left(\frac{\varepsilon_0}{\varepsilon} - 1 \right) l}{l + \frac{\varepsilon_0}{\varepsilon} (l+1)} \right) P_l(\cos \theta)
\end{aligned}$$

1.2

For $r/d \ll 1$, $l \geq 2$ terms are negligible. Thus, $\Phi_{\text{in}}(\vec{r})$ becomes:

$$\begin{aligned}\Phi_{\text{in}}(\vec{r}) &\approx \frac{q}{4\pi\epsilon_0 d} + \frac{q}{4\pi\epsilon d^2} \frac{3}{1 + 2\frac{\epsilon_0}{\epsilon}} \underbrace{r \cos \theta}_z \\ &= \frac{q}{4\pi\epsilon_0 d} + \frac{q}{4\pi\epsilon d^2} \frac{3}{1 + 2\frac{\epsilon_0}{\epsilon}} z\end{aligned}$$

Because $\vec{E} = -\nabla\Phi$:

$$\boxed{E = -\frac{q}{4\pi\epsilon d^2} \frac{3}{1 + 2\frac{\epsilon_0}{\epsilon}} \hat{z}}$$

1.3

Our solution for Φ_{in} in part a is:

$$\begin{aligned}\Phi_{\text{in}}(\vec{r}) &= \frac{q}{4\pi\epsilon d} \sum_{l=0}^{\infty} \left(\frac{r}{d}\right)^l \frac{2l+1}{l + \frac{\epsilon_0}{\epsilon}(l+1)} P_l(\cos \theta) \\ &= \frac{q}{4\pi\epsilon_0 d} \sum_{l=0}^{\infty} \left(\frac{r}{d}\right)^l \frac{2l+1}{\frac{\epsilon}{\epsilon_0}l + (l+1)} P_l(\cos \theta)\end{aligned}$$

For $\epsilon/\epsilon_0 \rightarrow \infty$, all the terms in the series go to zero, except for the $l = 0$ term:

$$\boxed{\Phi_{\text{in}} = \frac{q}{4\pi\epsilon_0 d}}$$

For $\epsilon/\epsilon_0 \rightarrow \infty$, our solution for Φ_{out} in part a becomes:

$$\Phi_{\text{out}}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{a}{rd} + \frac{q}{4\pi\epsilon_0} \sum_{l=0}^{\infty} \left(\frac{r_{<}^l}{r_{>}^{l+1}} - \frac{a^{2l+1}}{(rd)^{l+1}} \right) P_l(\cos \theta)$$

Note that the extra term out front comes due to the fact that ϵ_0/ϵ doesn't vanish when it multiplies l when $l = 0$. However, ϵ_0/ϵ vanishes for all other terms in the series.

$$\Phi_{\text{out}}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{a}{rd} + \frac{q}{4\pi\epsilon_0} \underbrace{\sum_{l=0}^{\infty} \frac{r_{<}^l}{r_{>}^{l+1}} P_l(\cos \theta)}_{1/|\vec{r}-d\hat{z}|} - \frac{qa}{4\pi\epsilon_0} \underbrace{\sum_{l=0}^{\infty} \frac{a^{2l}}{(rd)^{l+1}} P_l(\cos \theta)}_{1/|a^2\hat{z}-d\vec{r}|}$$

$$\boxed{\Phi_{\text{out}}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \left[\frac{a}{rd} + \frac{1}{|\vec{r}-d\hat{z}|} - \frac{a/d}{|\frac{a^2}{d}\hat{z}-\vec{r}|} \right]}$$

$\Phi_{\text{out}}(\vec{r})$ agrees with equation 2.8 in Jackson. Note that we have $\Phi_{\text{in}}(a) = \Phi_{\text{out}}(a)$, as expected, and $\Phi_{\text{in}}(\vec{r})$ is constant, as expected, since the potential must remain constant inside a conductor. Hence, our solution for part a reduces to that of a conducting sphere in the limit $\varepsilon/\varepsilon_0 \rightarrow \infty$.

2 Problem 5.3

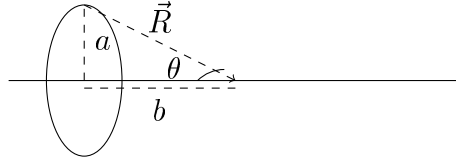


Figure 2: Single loop

Starting with the Biot-Savart Law for a loop with radius a and current I :

$$B = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times \vec{R}}{|\vec{R}|^3}$$

Noting that $d\vec{l} \times \vec{R} = dlR \sin \theta = dlR(a/R) = dla$:

$$\begin{aligned} B &= \frac{\mu_0 I}{4\pi} \int \frac{a}{R^3} dl \\ &= \frac{\mu_0 I}{4\pi} \frac{a}{R^3} (2\pi a) \\ &= \frac{\mu_0 I}{2} \frac{a^2}{(a^2 + b^2)^{3/2}} \end{aligned}$$

For N loops squished together, B just becomes:

$$B = \frac{\mu_0 N I}{2} \frac{a^2}{(a^2 + b^2)^{3/2}}$$

To account for the rings to the left of the observation point, we integrate from 0 to c :

$$B_{\text{left}} = \int_0^c \frac{\mu_0 N I}{2} \frac{a^2}{(a^2 + b^2)^{3/2}} db$$

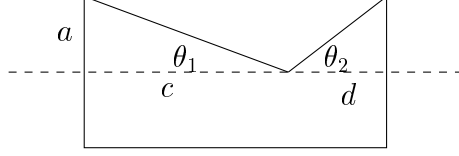


Figure 3:

Using the substitution $b = a \tan \theta$, $db = a \sec^2 \theta d\theta$:

$$\begin{aligned}
 B_{\text{left}} &= \int_0^{\arctan(c/a)} \frac{\mu_0 N I}{2} \frac{a^2}{a^3 \left(\underbrace{1 + \tan^2 \theta}_{\sec^2 \theta} \right)^{3/2}} a \sec^2 \theta d\theta \\
 &= \frac{\mu_0 N I}{2} \int_0^{\arctan(c/a)} \cos \theta d\theta \\
 &= \frac{\mu_0 N I}{2} \sin \left[\arctan \left(\frac{c}{a} \right) \right] \\
 &= \frac{\mu_0 N I}{2} \frac{c}{\sqrt{a^2 + c^2}} = \frac{\mu_0 N I}{2} \cos \theta_1
 \end{aligned}$$

To account for the rings to the right of the observation point, we integrate from 0 to d :

$$B_{\text{left}} = \int_0^d \frac{\mu_0 N I}{2} \frac{a^2}{(a^2 + b^2)^{3/2}} db$$

Using the substitution $b = a \tan \theta$, $db = a \sec^2 \theta d\theta$:

$$\begin{aligned}
 B_{\text{left}} &= \int_0^{\arctan(d/a)} \frac{\mu_0 N I}{2} \frac{a^2}{a^3 \left(\underbrace{1 + \tan^2 \theta}_{\sec^2 \theta} \right)^{3/2}} a \sec^2 \theta d\theta \\
 &= \frac{\mu_0 N I}{2} \int_0^{\arctan(d/a)} \cos \theta d\theta \\
 &= \frac{\mu_0 N I}{2} \sin \left[\arctan \left(\frac{d}{a} \right) \right] \\
 &= \frac{\mu_0 N I}{2} \frac{d}{\sqrt{a^2 + d^2}} = \frac{\mu_0 N I}{2} \cos \theta_2
 \end{aligned}$$

Finally, $B = B_{\text{left}} + B_{\text{right}}$:

$$B = \frac{\mu_0 N I}{2} (\cos \theta_1 + \cos \theta_2)$$

3 Problem 5.6

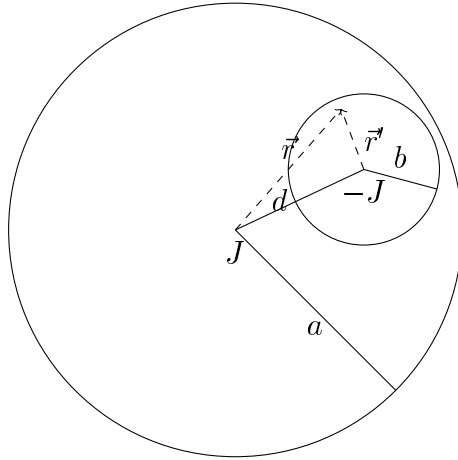


Figure 4: Setup for problem 5.6

We will consider two different systems and superimpose them (see figure 4).

1. A cylinder of radius a with current density $J\hat{z}$.
2. A cylinder of radius b with current density $-J\hat{z}$.

The B -field due to the cylinder in system 1 is:

$$\begin{aligned} \oint \vec{B} \cdot d\vec{l} &= \mu_0 \int \vec{J} \cdot dS \\ B2\pi r &= \mu_0 J\pi r^2 \\ \vec{B}_1 &= \frac{\mu_0}{2} J r \hat{\phi} \\ &= \frac{\mu_0}{2} J r (\hat{z} \times \hat{r}) \end{aligned}$$

The B -field due to the cylinder in system 2 is:

$$\begin{aligned} \oint \vec{B} \cdot d\vec{l} &= \mu_0 \int \vec{J} \cdot dS \\ B2\pi r' &= \mu_0 (-J)\pi r'^2 \\ \vec{B}_2 &= -\frac{\mu_0}{2} J r' \hat{\phi}' \\ &= -\frac{\mu_0}{2} J r' (\hat{z} \times \hat{r}') \end{aligned}$$

Superimposing these two systems yields $\vec{B} = \vec{B}_1 + \vec{B}_2$:

$$\begin{aligned}\vec{B} &= \frac{\mu_0}{2} J (r \hat{z} \times \hat{r} - r' \hat{z} \times \hat{r}') \\ &= \frac{\mu_0}{2} J \hat{z} \times \underbrace{(r \hat{r} - r' \hat{r}')}_{\vec{d}}\end{aligned}$$

$$\boxed{\vec{B} = \frac{\mu_0}{2} J \hat{z} \times \vec{d}}$$