



#### A Pin-Hole Projection System: Status

## Wolfgang Lorenzon

Work performed by:

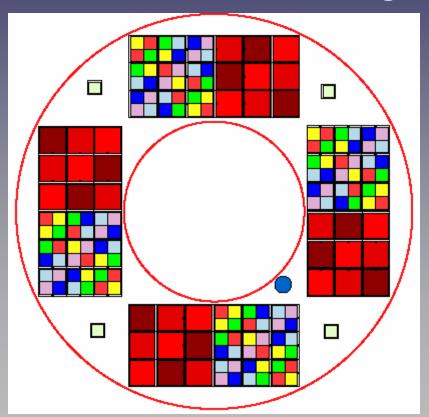
Michael Borysow Nate Barron

Wolfgang Lorenzon





### **SNAP** Detector Design



We need to test:
Intra-pixel response
Lateral Charge Diffusion

– Must shine a sub-pixel sized spot (~3  $\mu$ m dia) onto the detector, and be able to move it around VERY precisely





## Detector Design



#### Detector to be tested is mounted inside a dewar to keep it at 140K.

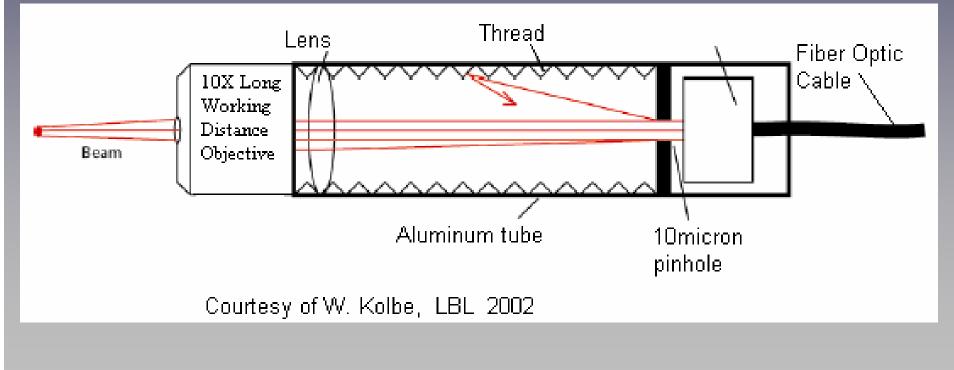
# Dewar necessitates a long working distance!

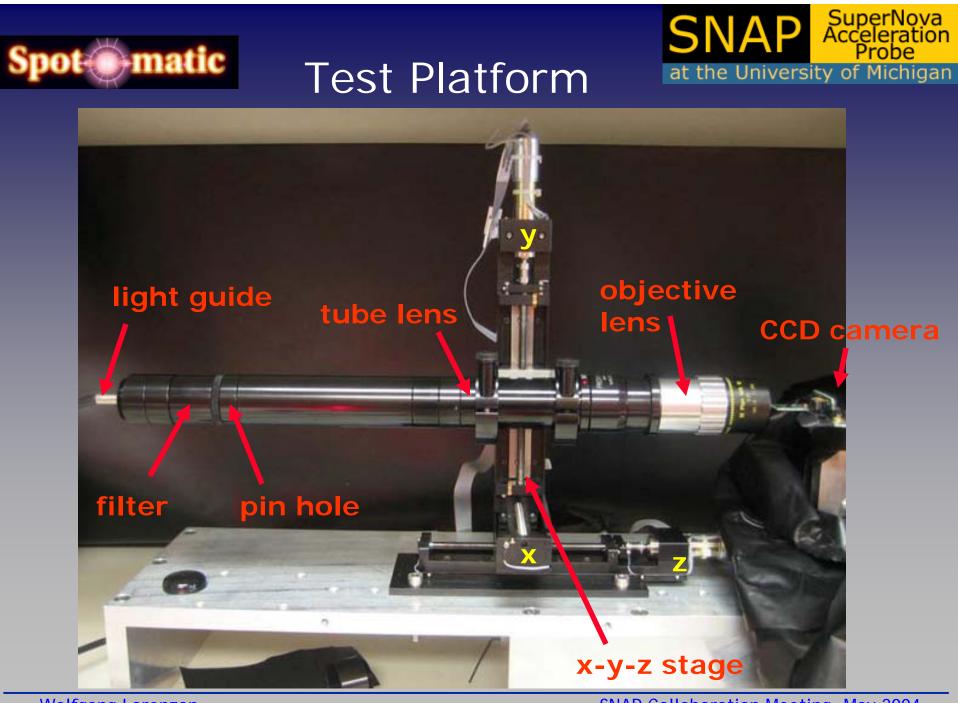




# Pinhole Projector

Idea borrowed from an LBL design, adapted for NIR light.





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## Properties

#### • optical:

- M Plan NIR series (Mitutoyo Long Working distance objective)
- magnification (microscope configuration): 10x
- range (chromatically corrected): 480-1800 nm
- numerical aperture (NA): 0.26  $\Rightarrow$  minimal spot size [=f( $\lambda$ )]: 0.96 - 3.6 $\mu$ m ( $\sigma$ )

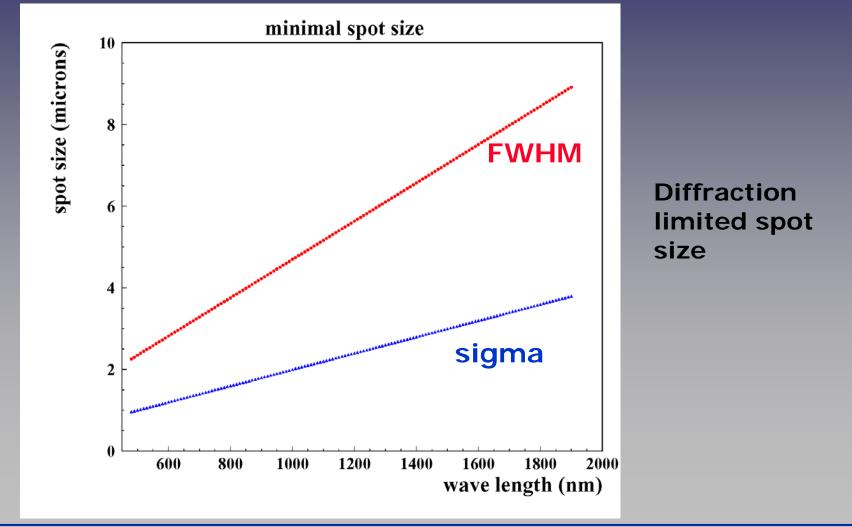
–XYZ stage:

- step size: 0.075  $\mu$ m (±1 $\mu$ m per inch of travel)
- CCD camera:
  - 3COM Homeconnect Webcam
  - 480x640 pixels (5x5  $\mu$ m<sup>2</sup> each)
- light source:
  - standard QT halogen lamp with fiber optics: 5% relative stability
  - Oriel Photomax 60100 with liquid light guide: 0.1% relative stability





## Properties (II)

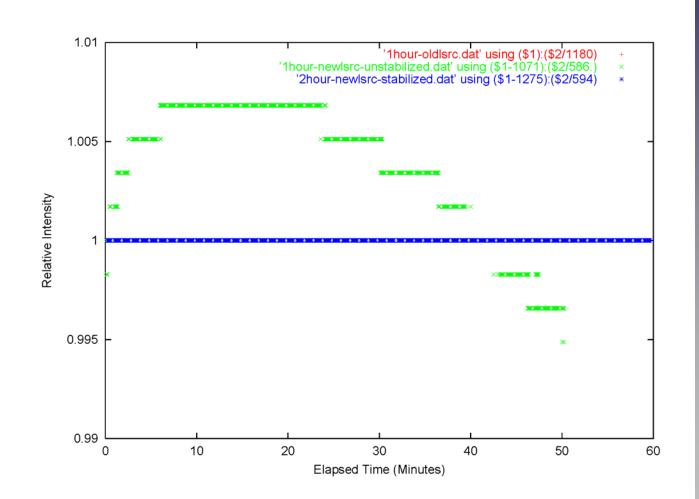


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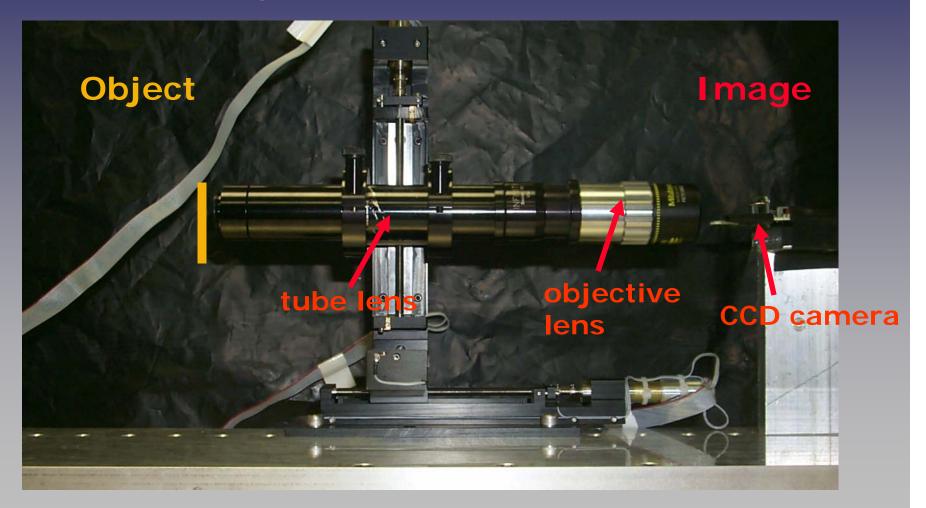
## Light Stability



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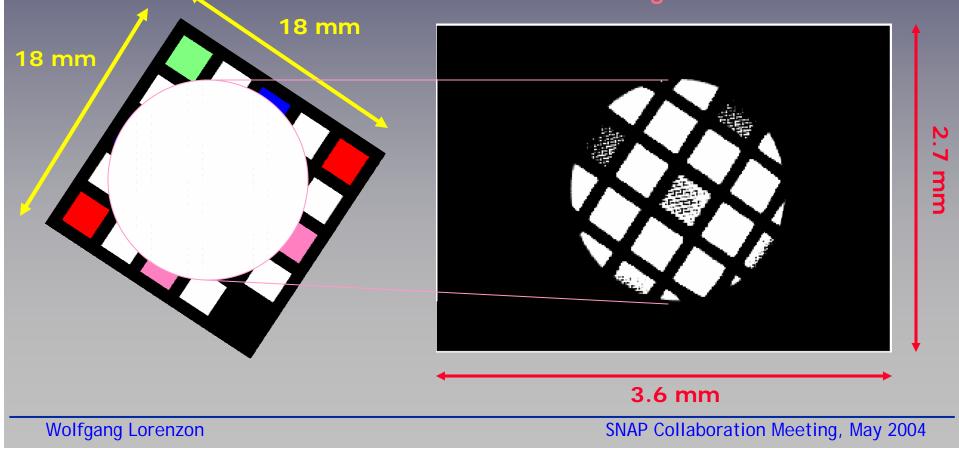
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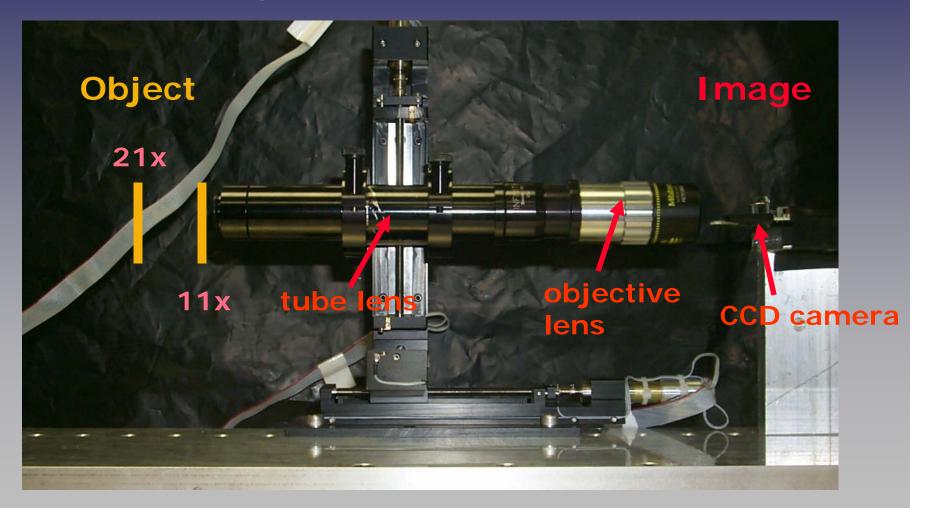


#### I mage on CCD Camera 11x demagnification









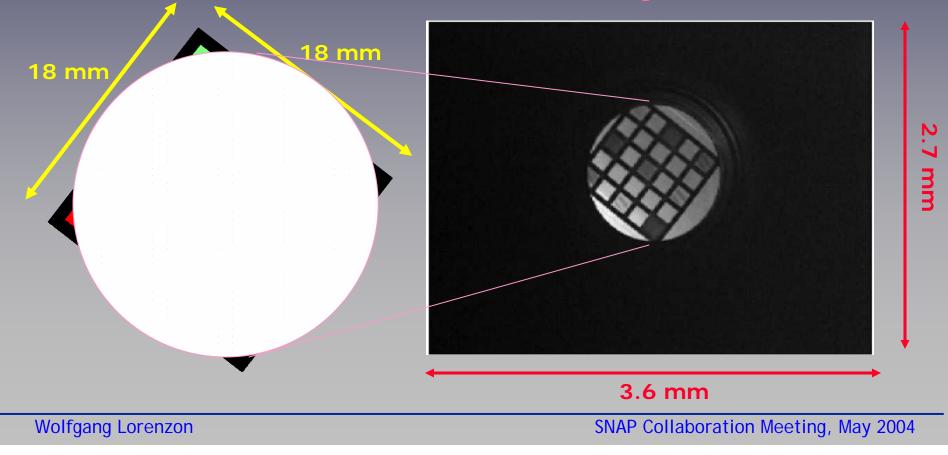
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Object

#### Image on CCD Camera 21x demagnification



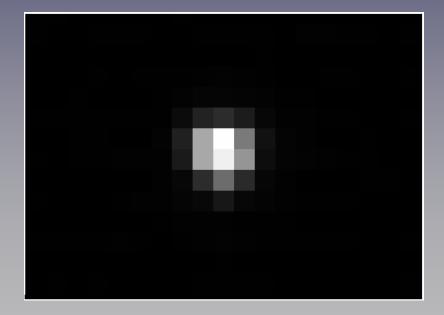




# Imaging pinholes

#### 100 $\mu$ m pinhole

#### 10 $\mu$ m pinhole



800 nm filter

no filter

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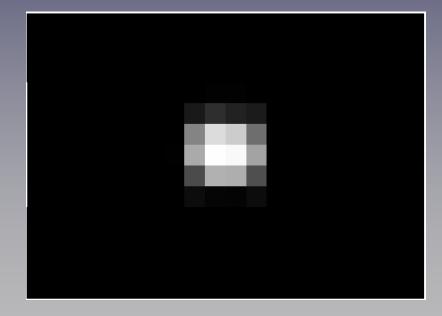


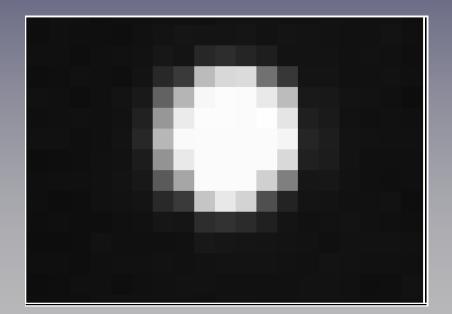


# Imaging pinholes

#### 10 $\mu$ m pinhole

#### +135 $\mu$ m off focus



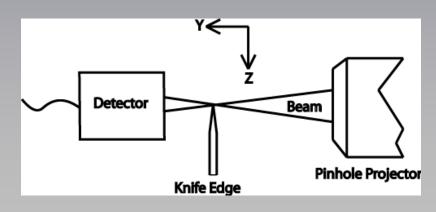


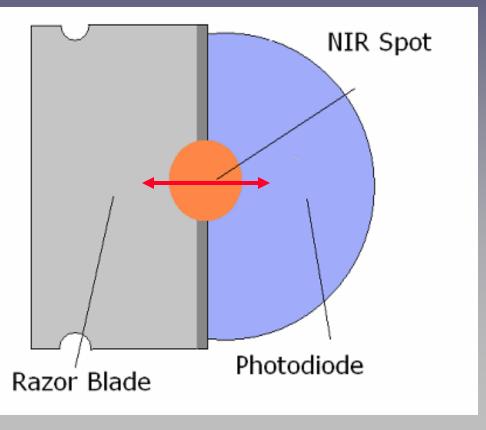




## How do you actually measure how big the spot really is?

- Use the knife-edge test to find the integral of intensity vs. position.
- Then take derivative to find the beam profile.



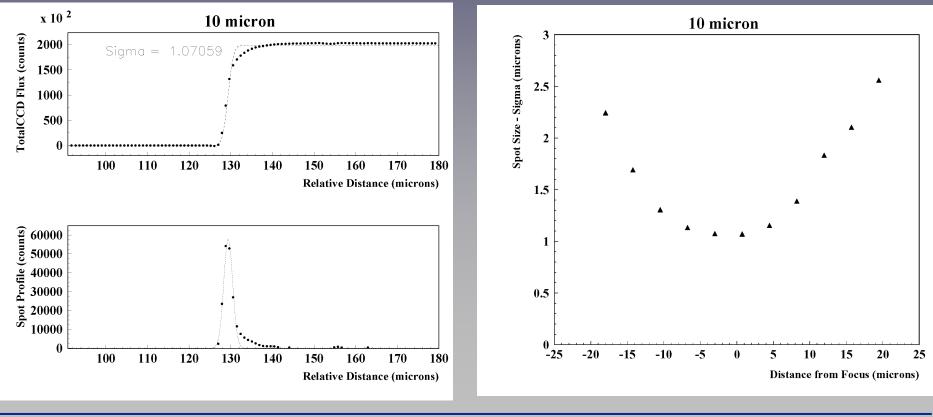


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Spot matic



# $\begin{array}{l} \mbox{Results} \\ \mbox{10 $\mu$m pinhole} \ \Rightarrow 2.5 $\mu$m (FWHM) spot on CCD \end{array}$

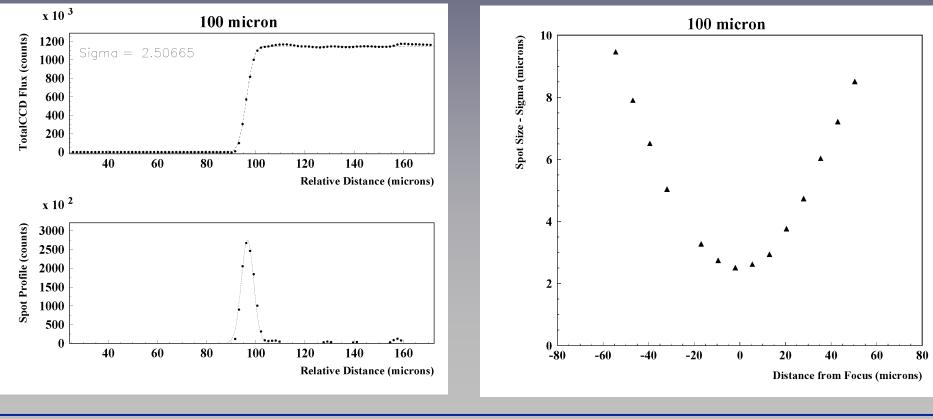


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Spot matic



# Results100 $\mu$ m pinhole $\Rightarrow$ 5.9 $\mu$ m (FWHM) spot on CCD



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# Results

#### Summary

Pinhole Size	Smallest spot on CCD	Expected spot size (no diffraction)	Expected spot size (incl. diffraction)
100 μ <b>m</b>	5.9 μm	<b>4.8 μm</b>	5.4 μm
10 μm	<b>2.5 μm</b>	0.48 μm	2.5 μm

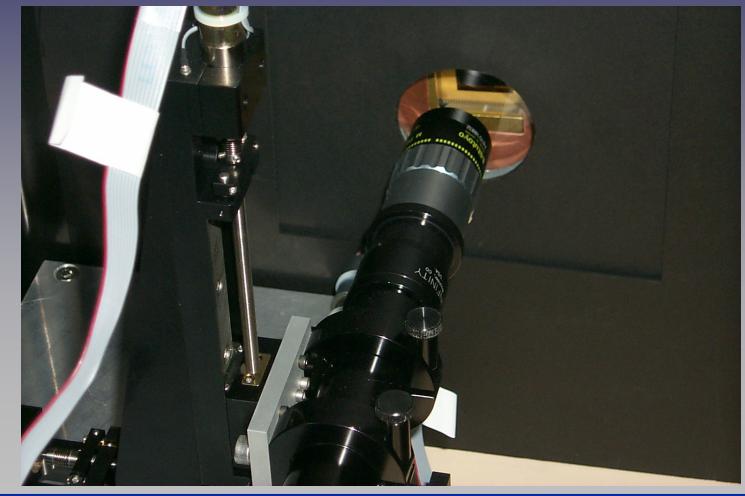
#### Demagnification: 21x

Resolving Power =  $0.61\lambda / N.A. \approx 1.2 \mu m$ .





# Putting a Spot on the InGaAs Detector

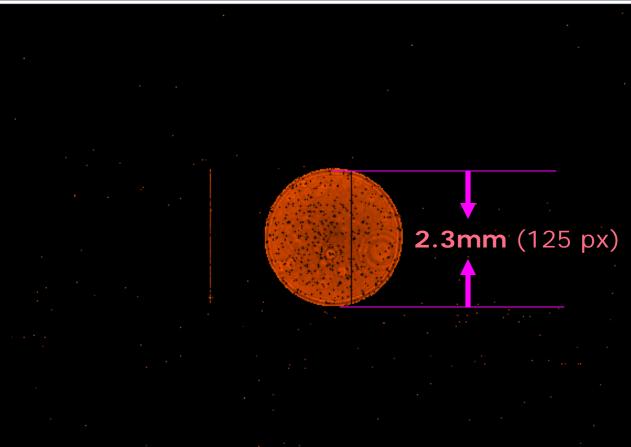


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# Putting a Spot on the InGaAs Detector (II)



filter: 1400 ± 50 nm

4.2mm from focus

standoffs ready to install

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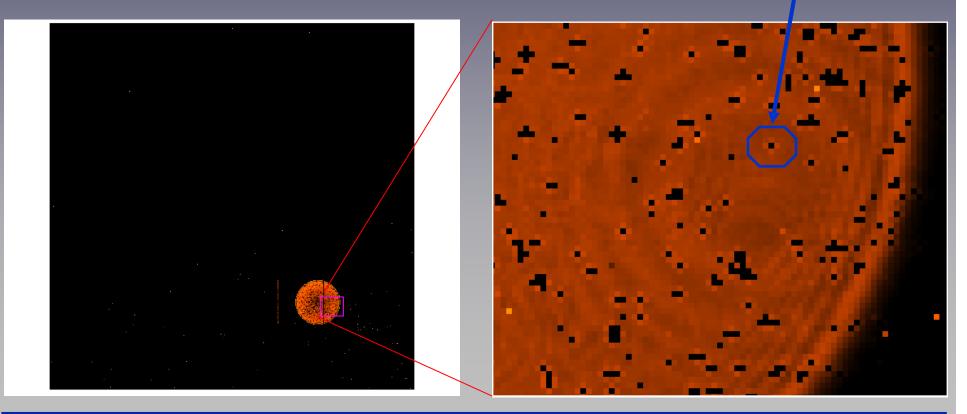




# Putting a Spot on the InGaAs Detector (III)

#### Full view (1k x 1k)

#### Zoomed in $\Rightarrow$ daisy-ing



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# Capabilities

• minimal spot sizes: 0.96 – 3.6  $\mu$ m ( $\sigma$ ) for  $\lambda$ =480-1800 nm

- mapping out pixel response function
- requires deconvolution of PSF of spot-o-matic as determined by knife edge tests (known) and pixel response function (unknown)
- study lateral charge diffusion
- any spot size above diffraction limit available by
  - defocussing minimal spot
  - using larger pin holes
- can simulate airy disks for SNAP focal plane
  - evaluation of dithering schemes
- daisy-ing effect:
  - peculiar situation
  - another handle on charge diffusion using spot-o-matic?





## Summary

- Pin Projection system tested using CCD
  - fully automated
  - NIR operation
- first image on a InGaAs device
- minor modifaction on dewar needed
  - project spots within 1 week on InGaAs detector
- ready to measure
  - intra-pixel response of HgCdTl and InGaAs detectors
  - lateral charge diffusion
- embark on program to partially characterize pixel response function
  - $-2\mu$ m rastering: 81 exposures per pixel (2 min ea)
    - $\Rightarrow$  16 yrs per device !!
  - full characterization NOT feasible