

## BASICS

I assume that everyone knows the theorem of implicit functions and the inverse mapping theorem. However, these theorems are so central that I will prove them. I also prove the theorem of existence and uniqueness of solutions of ODEs. The proofs here are not absolutely complete; for complete proofs look at any good calculus book.

A metric space  $(X, d_X)$  is complete if every Cauchy sequence in  $X$  converges, i.e. every sequence  $(x_i)$  such that for all  $\epsilon > 0$  there is  $i_\epsilon$  with  $d_X(x_i, x_j) < \epsilon$  for all  $i, j > i_\epsilon$ .

**Question 1.** *By construction,  $(\mathbb{R}, |\cdot|)$  is complete.*

- (1) *Let  $(X, d_X), (Y, d_Y)$  be metric spaces and consider the  $C^0(X, Y)$  be the set of all continuous maps  $f : X \rightarrow Y$  and set*

$$d_{C^0}(f, g) = \max_{x \in X} d_Y(f(x), g(x))$$

*Show that  $(C^0(X, Y), d_{C^0})$  is a complete metric space.*

- (2) *Assume that  $U \subset \mathbb{R}^n$  is open and let  $C^1(U)$  be the set of continuously differentiable maps  $f : U \rightarrow \mathbb{R}^m$  and set*

$$d_{C^1}(f, g) = d_{C^0}(f, g) + d_{C^0}(Df, Dg)$$

*Show that  $(C^1(U), d_{C^1})$  is a complete metric space.*

- (3) *Let  $l^2$  be the set of all sequence  $(a_i)$  with index set  $\mathbb{N}$  and  $a_i \in \mathbb{R}$  with such that the series  $\sum_i |a_i|^2$  converges and set*

$$d_{l^2}((a_i), (b_i)) = \sqrt{\sum_i |a_i - b_i|^2}$$

*Prove that  $(l_2, d_{l_2})$  is a complete metric space.*

A map  $f : (X, d_X) \rightarrow (Y, d_Y)$  between two metric spaces is  $L$ -Lipschitz if for all  $x_1, x_2 \in X$  we have

$$d_Y(f(x_1), f(x_2)) \leq L d_X(x_1, x_2)$$

**Question 2.**

- (1) *Assume that  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is continuously differentiable and that for all  $x \in \mathbb{R}^n$*

$$\|Df|_x\| = \max_{v \in \mathbb{R}^n, v \neq 0} \frac{\|Df_x v\|}{\|v\|} \leq L$$

*Show that  $f$  is  $L$ -Lipschitz.*

- (2) Construct a continuous function  $f : \mathbb{R} \rightarrow \mathbb{R}$  which is differentiable almost everywhere with  $f'(x) = 0$  but which is not Lipschitz.

A map  $f : X \rightarrow X$  has a fix-point if there is  $x \in X$  with  $f(x) = x$ . The point  $x$  is then said to be a fix-point.

**Banach fix-point theorem.** Let  $(X, d_X)$  be a complete metric space and  $f : X \rightarrow X$  a  $L$ -Lipschitz map with  $L < 1$ . Then  $f$  has a fix-point.

*Proof.* Pick  $x \in X$ , set  $x_0 = x$  and define inductively  $x_{n+1} = f(x_n)$ . For all  $n \geq 1$  we have then

$$d_X(x_{n+1}, x_n) = d_X(f(x_n), f(x_{n-1})) \leq L d_X(x_n, x_{n-1})$$

Inductively one has  $d_X(f(x_{n+1}), x_n) \leq L^n d(x_1, x_0)$ . This implies then that for all  $n, k \geq 1$  one has

$$\begin{aligned} d_X(x_{n+k}, x_n) &\leq \sum_{j=0}^{k-1} d_X(x_{n+j+1}, x_{n+j}) \leq \sum_{j=0}^{k-1} L^{n+j} d_X(x_1, x_0) \\ &= \frac{1 - L^k}{1 - L} L^n d_X(x_1, x_0) \end{aligned}$$

Since  $L < 1$ , this implies that the sequence  $(x_i)$  is a Cauchy-sequence. In particular, it converges to some  $x_\infty$ . We have then

$$x_\infty = \lim_{i \rightarrow \infty} x_i = \lim_{i \rightarrow \infty} x_{i+1} = \lim_{i \rightarrow \infty} f(x_i) = f(x_\infty)$$

Hence  $x_\infty$  is the desired fix-point. □

### Question 3.

- (1) Prove that the fix-point is unique.
- (2) Construct a 1-Lipschitz map  $\mathbb{R} \rightarrow \mathbb{R}$  without fix-points.
- (3) Prove that if  $f : (X, d) \rightarrow (X, d)$  is continuous, surjective and  $d(f(x), f(y)) \geq 2d(x, y)$  for all  $x, y$  then  $f$  has a fix-point.
- (4) Construct an example showing that the condition that  $f$  is surjective in (2) is necessary.

**Implicit function theorem.** Let  $U_1 \subset \mathbb{R}^k$  and  $U_2 \subset \mathbb{R}^m$  be open sets and

$$F : U_1 \times U_2 \rightarrow \mathbb{R}^m, (x, y) \mapsto F(x, y)$$

be a continuously differentiable map. Given  $(a, b) \in U_1 \times U_2$  with  $F(a, b) = 0$  assume that the linear map  $\frac{\partial F}{\partial y}|_{(a,b)}$  is invertible. Then there are  $V_1 \subset U_1$  and  $V_2 \subset U_2$  open neighborhoods of  $a$  and  $b$  respectively and a continuously differentiable map

$$f : V_1 \rightarrow V_2$$

with  $f(a) = b$  such that  $F(x, f(x)) = 0$  for all  $x \in V_1$ . Moreover, the map  $x \mapsto (x, f(x))$  maps onto the set  $(V_1 \times V_2) \cap F^{-1}(0)$ .

*Proof.* Assume without loss of generality that  $(a, b) = (0, 0)$  and let  $B = \frac{DF}{\partial Y}|_{(0,0)} \in \text{GL}_m \mathbb{R}$ . Set

$$G : U_1 \times U_2 \rightarrow \mathbb{R}^m, \quad G(x, y) = y - B^{-1}F(x, y)$$

and observe that

$$G(0, 0) = 0, \quad \frac{\partial G}{\partial y}|_{(0,0)} = 0$$

Observe also that  $F(x, y) = 0$  if and only if  $G(x, y) = y$ .

By continuity we have small closed balls  $V_1 \subset U_1$  and  $V_2 \subset U_2$  of 0 with

$$\|\partial G_{(x,y)}\| \leq \frac{1}{2}$$

for all  $x, y \in V_1 \times V_2$ .

**For simplicity** we assume that  $G(V_1 \times V_2) \subset V_2$ ; otherwise one has to choose further smaller balls.

For all  $x \in V_1$ , the map

$$V_2 \rightarrow V_2, \quad y \mapsto G(x, y)$$

is  $\frac{1}{2}$ -Lipschitz and hence has a unique fixed point  $y$ . Set  $f(x) = y$ .

So far, we have that  $f : V_1 \rightarrow V_2$  parametrizes the set  $(V_1 \times V_2) \cap F^{-1}(0)$ . The continuity of the map follows directly. For the smoothness one has to work a bit more.  $\square$

**Question 4.** *Prove that the map  $f$  in the implicit function theorem is smooth and compute its differential.*

**Inverse mapping theorem.** *Let  $U \subset \mathbb{R}^n$  be open and  $f : U \rightarrow \mathbb{R}^n$  a continuously differentiable function. Assume that for some  $x \in U$  the differential  $Df|_x$  has maximal rank. Then there are small neighborhoods  $V$  of  $x$  and  $W$  of  $f(x)$  with  $f(V) = W$  and a smooth map  $g : W \rightarrow V$  with  $f \circ g = \text{Id}$  and  $g \circ f = \text{Id}$ .*

*Proof.* Consider the map  $F : \mathbb{R}^n \times U \rightarrow \mathbb{R}^n$  given by  $F(y, x) = y - f(x)$ . The assumptions on the theorem of implicit functions are satisfied. The map  $g$  provided by the implicit function theorem fulfills

$$0 = F(y, g(y)) = y - f(g(y))$$

and hence it does the job.  $\square$

Let  $U \subset \mathbb{R}^n$  be open and  $F : U \rightarrow \mathbb{R}^n$  be a map. Under a solution of the first order ODE  $\gamma' = F(\gamma)$  we understand a map

$$\gamma : I \rightarrow U$$

with  $\gamma'(t) = F(\gamma(t))$  for all  $t \in I$ . Here  $I$  is a subinterval of  $\mathbb{R}$ . Fixing  $x \in U$  we say that a solution solves the initial value problem determined by  $x$  if  $\gamma(0) = x$ .

The definition of a second, third, etc... order ordinary differential equation is similar. One can reduce the discussion of the higher order ODEs as follows. In order to understand  $y'' = y$  it suffices to solve  $(y'_1, y'_2) = (y_2, y_1)$  and take the  $y_1$ -component. One can use a similar trick to solve time-dependent equations.

The main theorem here is the following:

**Existence and uniqueness theorem** (Picard-Lindelöf). *Assume that  $U \subset \mathbb{R}^n$  is open and  $F : U \rightarrow \mathbb{R}^n$  satisfies a local Lipschitz condition. Then for every  $x \in U$  there is  $\epsilon > 0$  and a curve  $\gamma : (-\epsilon, \epsilon) \rightarrow U$  with*

$$\gamma(0) = x \quad \text{and} \quad \gamma'(t) = F(\gamma(t)) \quad \text{for all } t$$

Moreover, any two solutions  $\gamma, \eta$  coincide on a small neighborhood of  $0 \in \mathbb{R}$ .

*Proof.* Up to reducing  $U$  we may assume that it is the ball of radius  $1 > r > 0$  around  $x = 0$  and that  $F$  is  $L$ -Lipschitz on  $U$  for some  $L$ . Observe also that for  $\lambda > 0$  solutions of the original problem are related by solutions of

$$\gamma' = \lambda F(\gamma(x))$$

by a time change; replace namely  $\gamma(t)$  by  $\gamma(\lambda t)$ . Choosing then  $\lambda$  very small we may assume that  $F$  is actually  $\frac{1}{2}$ -Lipschitz and that  $\max_{y \in U} \|F(y)\| \leq \frac{1}{2}$ .

We consider now the set  $X$  of  $C^1$ -curves  $\gamma : [0, r) \rightarrow U$  with  $\gamma(0) = 0$  and such that  $\max_t |\gamma'(t)| \leq 1$ . With respect to the  $d_{C^1}$ -distance,  $X$  is a complete metric space.

Given  $\gamma \in X$  let  $\Phi_\gamma$  be the curve

$$\Phi_\gamma(t) = \int_0^t F(\gamma(s)) ds$$

Observe that  $\Phi_\gamma(0) = 0$  and that for all  $t$  we have

$$\Phi'_\gamma(t) = \frac{d}{dt} \int_0^t F(\gamma(s)) ds = F(\gamma(t))$$

In particular,  $\|\Phi'_\gamma(t)\| \leq \frac{1}{2}$  for all  $t$  and hence  $\Phi_\gamma \in X$ .

Let's estimate the Lipschitz constant of  $\gamma \mapsto \Phi_\gamma$ .

$$\begin{aligned} \|\Phi_\gamma(t) - \Phi_\eta(t)\| &\leq \int_0^t \|F(\gamma(s)) - F(\eta(s))\| ds \\ &\leq t \frac{1}{2} \max_t \|\gamma(t) - \eta(t)\| \end{aligned}$$

$$\begin{aligned} \|\Phi'_\gamma(t) - \Phi'_\eta(t)\| &\leq \|F(\gamma(t)) - F(\eta(t))\| \\ &\leq \frac{1}{2} \|\gamma(t) - \eta(t)\| \end{aligned}$$

Taking both computations into account we obtain that

$$d_{C^1}(\Phi_\gamma, \Phi_\eta) \leq \frac{1}{2} d_{C^0}(\gamma, \eta) \leq \frac{1}{2} d_{C^1}(\gamma, \eta)$$

This means that  $\Phi : X \rightarrow X$  is  $\frac{1}{2}$ -Lipschitz and hence has a unique fix-point  $\gamma$ . The curve  $\gamma$  is our desired solution.  $\square$

Things to say:

- (1) Maximal solutions
- (2) Complete vector fields.
- (3) Flow.

### Question 5.

- (1) Construct a non-complete vector field on  $\mathbb{R}^2$ .
- (2) Prove that any bounded vector field is complete.
- (3) Assume that  $F$  is a complete vector field on  $\mathbb{R}^n$  and let for  $x \in \mathbb{R}^n$  be  $\gamma_x$  be the solution to the ODE  $\gamma'_x(t) = F(\gamma_x(t))$  and  $\gamma_x(0) = x$ . Prove that the map  $(x, t) \mapsto \gamma_x(t)$  is continuous.

**Dependence on initial values.** Assume that  $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is continuously differentiable and let for all  $x \in \mathbb{R}^n$  be  $\gamma_x$  be the solution to the initial value problem  $\gamma'_x = F \circ \gamma_x$  and  $\gamma_x(0) = x$ . Then the map  $(x, t) \mapsto \gamma_x(t)$  is continuously differentiable.