

Model-based X-ray CT image reconstruction using variable splitting methods with ordered subsets

Hung Nien (粘紘)

Advisor: Prof. Jeffrey A. Fessler

University of Michigan, Ann Arbor

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- Supported in part by an equipment donation from Intel Corp.
- Sinogram data are provided by GE Healthcare

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- 1 Introduction
- 2 Background of X-ray CT and its reconstruction
- 3 Fast X-ray CT image reconstruction using VS methods with OS
 - [HN & J A Fessler, Fully 3D, 2013]
 - [HN & J A Fessler, SPIE MI, 2014]
 - [HN & J A Fessler, CT Meeting, 2014]
 - [HN & J A Fessler, arXiv:1402.4381, 2014]
- 4 Blind gain correction for X-ray CT image reconstruction
 - [HN & J A Fessler, SPIE MI, 2013]
- 5 Model-based light field reconstruction
- 6 Conclusion and future work

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 - Fast (2D) CT reconstruction using ADMM
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 - Linearized AL method with OS acceleration
 - Deterministic downward continuation approach
 - Low-memory OS-LALM with additional variable splits
- 3 Experimental results
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What is computed tomography?

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Projection radiography

An imaging technique that uses X-rays to view the internal structure of a non-uniformly composed and opaque object such as the human body.

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Computed tomography

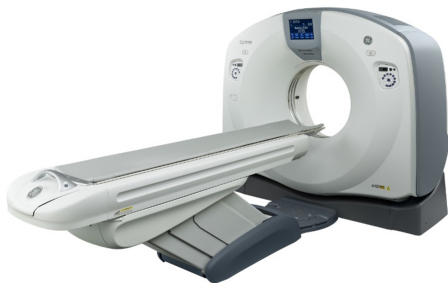
An imaging technique that combines a series of X-ray projections taken from many different angles and computer processing (i.e., reconstruction methods) to create cross-sectional images of the bones and soft tissues inside to the human body.

What is computed tomography?

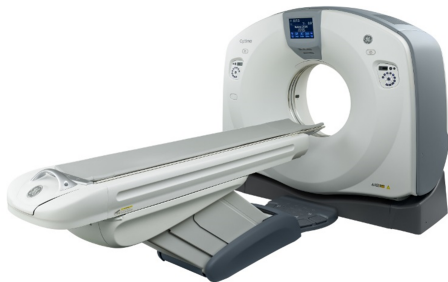
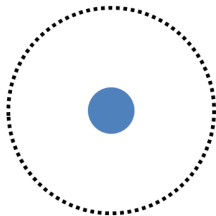


Figure: Chest X-ray image (left) and cross-sectional image of abdomen (right).

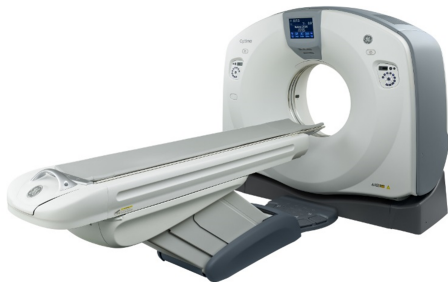
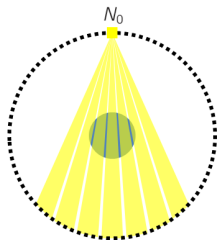
Basics of X-ray computed tomography



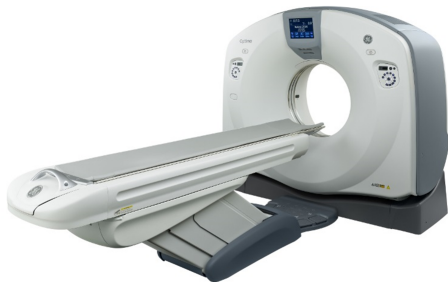
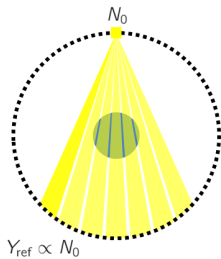
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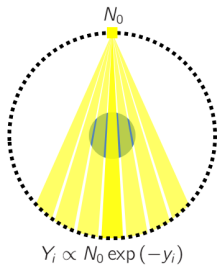
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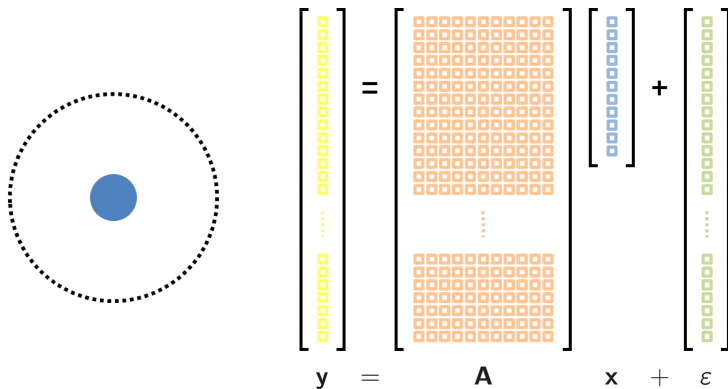
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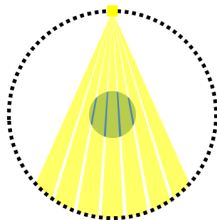
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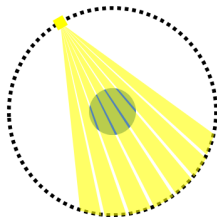


Basics of X-ray computed tomography



$$\begin{array}{c}
 \left[\begin{array}{c} \text{yellow squares} \\ \vdots \\ \text{yellow squares} \end{array} \right] = \left[\begin{array}{c} \text{orange grid} \\ \vdots \\ \text{orange grid} \end{array} \right] \left[\begin{array}{c} \text{blue squares} \end{array} \right] + \left[\begin{array}{c} \text{green squares} \\ \vdots \\ \text{green squares} \end{array} \right] \\
 \mathbf{y} = \mathbf{A} \mathbf{x} + \boldsymbol{\varepsilon}
 \end{array}$$

Basics of X-ray computed tomography



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$y = A x + \varepsilon$

Image reconstruction methods

Non-iterative methods

Iterative methods

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- Direct Fourier reconstruction

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- Maximum *a posteriori* (MAP) formulation
- Penalized weighted least-squares (PWLS) formulation [TS⁺07]

$$\hat{\mathbf{x}} \in \arg \min_{\mathbf{x} \in \Omega} \left\{ \Psi(\mathbf{x}) \triangleq \frac{1}{2} \|\mathbf{y} - \mathbf{Ax}\|_{\mathbf{W}}^2 + R(\mathbf{x}) \right\}$$

Image reconstruction methods



Figure: Dose reduction: FBP (left), ASiR (middle), and MBIR (right).

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Image reconstruction methods

Large problem size

- \mathbf{x} : $512 \times 512 \times 100 \approx 3 \cdot 10^7$ unknown image volume
- \mathbf{y} : $888 \times 32 \times 7000 \approx 2 \cdot 10^8$ measured noisy sinogram
- \mathbf{A} : $(3 \cdot 10^7) \times (2 \cdot 10^8)$ system matrix
- \mathbf{A} is sparse but still too large to store
- Projection \mathbf{Ax} and back-projection $\mathbf{A}'\mathbf{r}$ operations computed on the fly
- Computing gradient $\nabla\Psi(\mathbf{x}) = \mathbf{A}'\mathbf{W}(\mathbf{Ax} - \mathbf{y}) + \nabla R(\mathbf{x})$ requires projection and back-projection operations that dominate computation

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Enormous dynamic range of transmission data

- The dynamic range of weighting \mathbf{W} is huge
- $\mathbf{A}'\mathbf{WA}$ is highly shift-variant, and the problem is very ill-conditioned

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- **Very slow** (hours) but **noise robust** (low dose)

Image reconstruction methods

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Fast iterative methods

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CT reconstruction using split Bregman method

Equivalent formulation and split Bregman method

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Equivalent formulation and split Bregman method

- PWLS CT reconstruction: $\hat{\mathbf{x}} \in \arg \min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{Ax}\|_{\mathbf{W}}^2 + \Phi(\mathbf{Cx}) \right\}$

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- Equivalent formulation [GO09]:

$$(\hat{\mathbf{x}}, \hat{\mathbf{v}}) \in \arg \min_{\mathbf{x}, \mathbf{v}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{Ax}\|_{\mathbf{W}}^2 + \Phi(\mathbf{v}) \right\} \text{ s.t. } \mathbf{v} = \mathbf{Cx}$$

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- Corresponding (scaled) augmented Lagrangian:

$$\mathcal{L}_A(\mathbf{x}, \mathbf{v}, \mathbf{e}; \eta) \triangleq \frac{1}{2} \|\mathbf{y} - \mathbf{Ax}\|_{\mathbf{W}}^2 + \Phi(\mathbf{v}) + \frac{\eta}{2} \|\mathbf{Cx} - \mathbf{v} - \mathbf{e}\|_2^2$$

CT reconstruction using split Bregman method

Equivalent formulation and split Bregman method (cont'd)

- Split Bregman iterates [GO09]:

$$\begin{cases} \mathbf{x}^{(k+1)} \in \arg \min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{Ax}\|_{\mathbf{W}}^2 + \frac{\eta}{2} \|\mathbf{Cx} - \mathbf{v}^{(k)} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{v}^{(k+1)} \in \arg \min_{\mathbf{v}} \left\{ \Phi(\mathbf{v}) + \frac{\eta}{2} \|\mathbf{Cx}^{(k+1)} - \mathbf{v} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{e}^{(k+1)} = \mathbf{e}^{(k)} - \mathbf{Cx}^{(k+1)} + \mathbf{v}^{(k+1)} \end{cases}$$

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- Convergent with inexact updates [NF14a]
- Slow \mathbf{x} -update due to the highly shift-variant Hessian $\mathbf{A}'\mathbf{W}\mathbf{A} + \eta\mathbf{C}'\mathbf{C}$

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Alternative formulation and ADMM

- Alternative formulation [RF12]:

$$(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{\mathbf{v}}) \in \arg \min_{\mathbf{x}, \mathbf{u}, \mathbf{v}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{u}\|_{\mathbf{W}}^2 + \Phi(\mathbf{v}) \right\} \text{ s.t. } \mathbf{u} = \mathbf{A}\mathbf{x}, \mathbf{v} = \mathbf{C}\mathbf{x}$$

Better conditioning with additional VS

Alternative formulation and ADMM (cont'd)

- ADMM iterates [RF12]:

$$\begin{cases} \mathbf{x}^{(k+1)} \in \arg \min_{\mathbf{x}} \left\{ \frac{\rho}{2} \|\mathbf{Ax} - \mathbf{u}^{(k)} - \mathbf{d}^{(k)}\|_2^2 + \frac{\eta}{2} \|\mathbf{Cx} - \mathbf{v}^{(k)} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{u}^{(k+1)} \in \arg \min_{\mathbf{u}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{u}\|_{\mathbf{W}}^2 + \frac{\rho}{2} \|\mathbf{Ax}^{(k+1)} - \mathbf{u} - \mathbf{d}^{(k)}\|_2^2 \right\} \\ \mathbf{v}^{(k+1)} \in \arg \min_{\mathbf{v}} \left\{ \Phi(\mathbf{v}) + \frac{\eta}{2} \|\mathbf{Cx}^{(k+1)} - \mathbf{v} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{d}^{(k+1)} = \mathbf{d}^{(k)} - \mathbf{Ax}^{(k+1)} + \mathbf{u}^{(k+1)} \\ \mathbf{e}^{(k+1)} = \mathbf{e}^{(k)} - \mathbf{Cx}^{(k+1)} + \mathbf{v}^{(k+1)} \end{cases}$$

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$$\begin{cases} \mathbf{x}^{(k+1)} \in \arg \min_{\mathbf{x}} \left\{ \frac{\rho}{2} \|\mathbf{Ax} - \mathbf{u}^{(k)} - \mathbf{d}^{(k)}\|_2^2 + \frac{\eta}{2} \|\mathbf{Cx} - \mathbf{v}^{(k)} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{u}^{(k+1)} \in \arg \min_{\mathbf{u}} \left\{ \frac{1}{2} \|\mathbf{y} - \mathbf{u}\|_{\mathbf{W}}^2 + \frac{\rho}{2} \|\mathbf{Ax}^{(k+1)} - \mathbf{u} - \mathbf{d}^{(k)}\|_2^2 \right\} \\ \mathbf{v}^{(k+1)} \in \arg \min_{\mathbf{v}} \left\{ \Phi(\mathbf{v}) + \frac{\eta}{2} \|\mathbf{Cx}^{(k+1)} - \mathbf{v} - \mathbf{e}^{(k)}\|_2^2 \right\} \\ \mathbf{d}^{(k+1)} = \mathbf{d}^{(k)} - \mathbf{Ax}^{(k+1)} + \mathbf{u}^{(k+1)} \\ \mathbf{e}^{(k+1)} = \mathbf{e}^{(k)} - \mathbf{Cx}^{(k+1)} + \mathbf{v}^{(k+1)} \end{cases}$$

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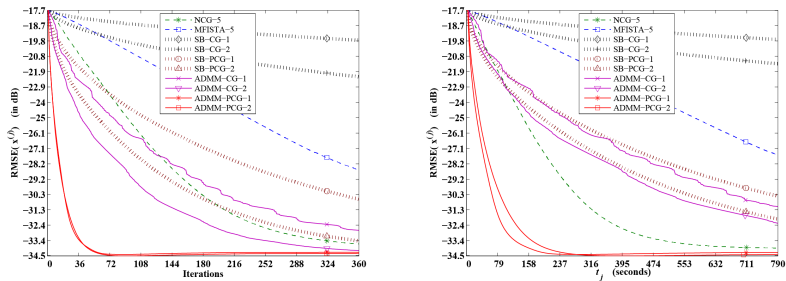


Figure: 2D NCAT: RMS errors as a function of iteration (left) and time (right).

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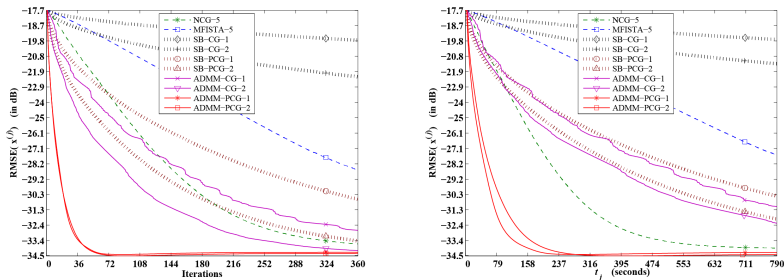


Figure: 2D NCAT: RMS errors as a function of iteration (left) and time (right).

The fact is ...

A'A is still highly shift-variant in 3D CT due to the different geometries and scan trajectories, so this method is still slow in 3D CT

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- Proposed formulation [NF13]:

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- Gradient-based linearized AL method [NF14b]:

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- But, it is **fast** only if the penalty parameter is **chosen appropriately**
- Choosing the optimal parameter is still an **open problem**

Any alternative?

- Yes, **continuation!**
- Recall the proximal-gradient image update:

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- An adaptive restart condition takes care of the dependence on $\tilde{\mathbf{A}}$

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OS-LALM with an additional VS

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CT reconstruction with “high-memory” VS

- PWLS formulation:

$$\hat{\mathbf{x}} \in \arg \min_{\mathbf{x} \in \Omega} \left\{ \frac{1}{2} \|\tilde{\mathbf{y}} - \tilde{\mathbf{A}}\mathbf{x}\|_2^2 + \Phi(\mathbf{C}\mathbf{x}) \right\}$$

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- Equivalent formulation [NF14c]:

$$(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{\mathbf{v}}) \in \arg \min_{\mathbf{x} \in \Omega, \mathbf{u}, \mathbf{v}} \left\{ \frac{1}{2} \|\tilde{\mathbf{y}} - \mathbf{u}\|_2^2 + \Phi(\mathbf{v}) \right\} \text{ s.t. } \mathbf{u} = \tilde{\mathbf{A}}\mathbf{x}, \mathbf{v} = \mathbf{C}\mathbf{x}$$

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$$\left\{ \begin{array}{l} \mathbf{s}^{(k+1)} = \rho \nabla \ell(\mathbf{x}^{(k)}) + (1 - \rho) \mathbf{g}^{(k)} \\ \boldsymbol{\sigma}^{(k+1)} = \bar{\eta} \mathbf{C}'(\mathbf{C}\mathbf{x}^{(k)} - \mathbf{v}^{(k)} - \mathbf{e}^{(k)}) \\ \mathbf{x}^{(k+1)} = \left[\mathbf{x}^{(k)} - \frac{1}{\rho L_1 + \bar{\eta} L_2} (\mathbf{s}^{(k+1)} + \boldsymbol{\sigma}^{(k+1)}) \right]_{\Omega} \\ \mathbf{g}^{(k+1)} = \frac{\rho}{\rho+1} \nabla \ell(\mathbf{x}^{(k+1)}) + \frac{1}{\rho+1} \mathbf{g}^{(k)} \\ \mathbf{v}^{(k+1)} \in \text{prox}_{\bar{\eta}^{-1}\Phi}(\mathbf{C}\mathbf{x}^{(k+1)} - \mathbf{e}^{(k)}) \\ \mathbf{e}^{(k+1)} = \mathbf{e}^{(k)} - \mathbf{C}\mathbf{x}^{(k+1)} + \mathbf{v}^{(k+1)} \end{array} \right.$$

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- Requires two extra image volumes for **each** direction
- Remarkable **memory** and **computational** overhead

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- At the k th iteration, replace Φ by

$$\check{\Phi}(\mathbf{v}; \mathbf{C}\mathbf{x}^{(k+1)}) \propto \mathbf{v}'\nabla\Phi(\mathbf{C}\mathbf{x}^{(k+1)}) + \frac{L_{\Phi}}{2} \|\mathbf{v} - \mathbf{C}\mathbf{x}^{(k+1)}\|_2^2$$

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- The \mathbf{v} -update has a linear approximate solution:

$$\mathbf{v}^{(k+1)} \approx \mathbf{C}\mathbf{x}^{(k+1)} - \left(\frac{\bar{\eta}}{\bar{\eta}+L_\Phi} \mathbf{e}^{(k)} + \frac{L_\Phi}{\bar{\eta}+L_\Phi} L_\Phi^{-1} \nabla\Phi(\mathbf{C}\mathbf{x}^{(k+1)}) \right)$$

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Setup and notation

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OS configuration

- OS with the bit-reversal order
- Separable quadratic surrogate with Hessian $\mathbf{D}_L \triangleq \text{diag}\{\mathbf{A}'\mathbf{W}\mathbf{A}\mathbf{1}\}$

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Naming conventions

- OS-SQS- M : the standard OS algorithm [EF99]
- OS-Nes05- M : the state-of-the-art OS+momentum algorithm [KR⁺13]
- OS-LALM- M - ρ - n : the proposed one-split algorithm [NF14b; NF14d]
- OS-LALM- M - c - η (low-mem): the proposed two-split algorithm

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Specification

- Image size: $512 \times 512 \times 109$
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Figure: Shoulder: the initial FBP image (left), the reference reconstruction (middle), and the reconstructed image using OS-LALM after 30 iterations (right).

Shoulder region helical scan

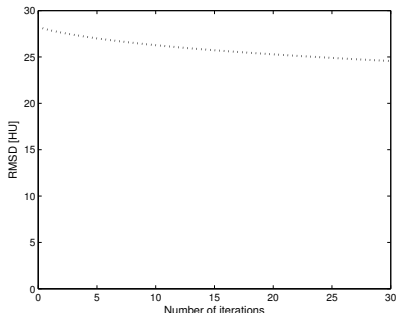


Figure: Shoulder: RMS differences as a function of iteration using different OS-based algorithms with 20 subsets (left) and 40 subsets (right).

Shoulder region helical scan

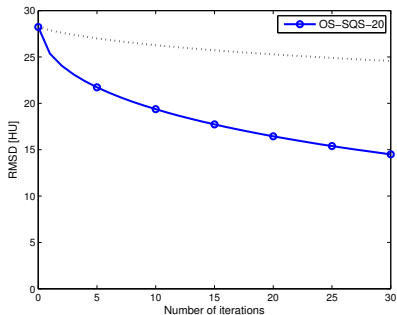


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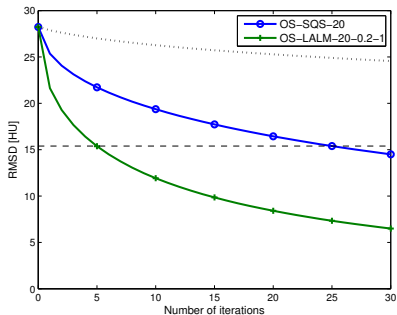


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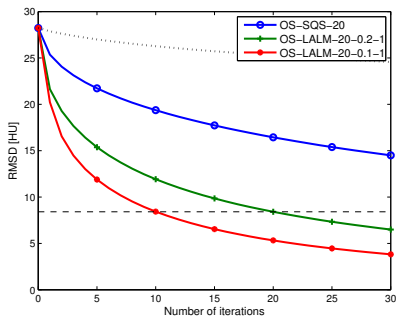


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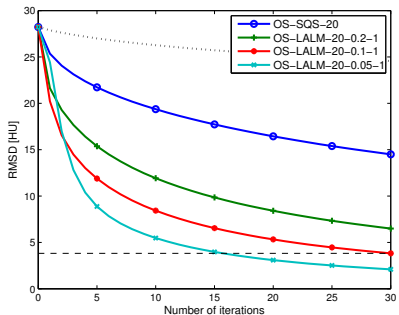


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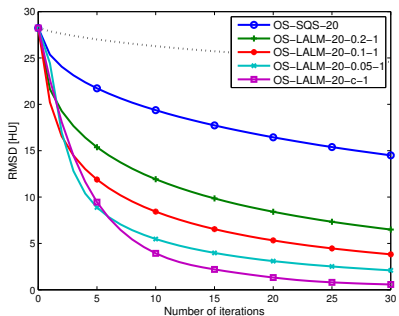


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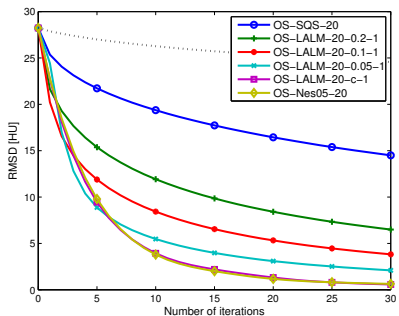


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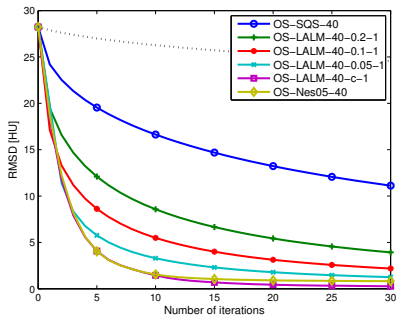
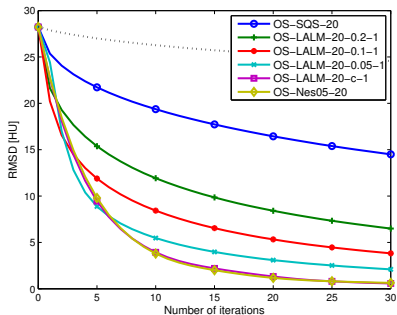


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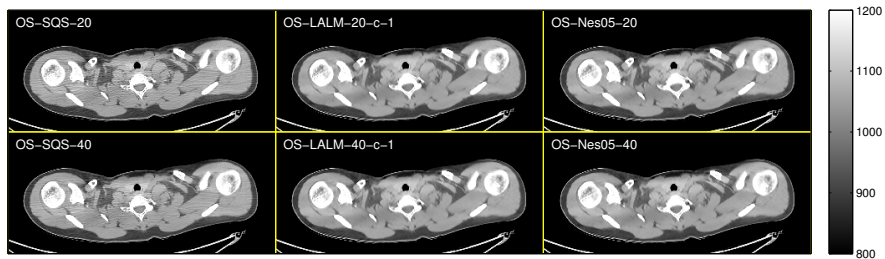


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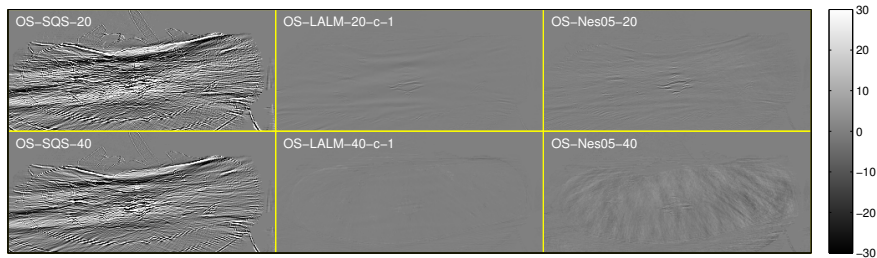


Figure: Shoulder: difference images of the reconstructed images using different OS-based algorithms after 30 iterations.

GE performance phantom axial scan

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- Sinogram size: $888 \times 64 \times 984$ (less view redundancy, cf. helical scan)

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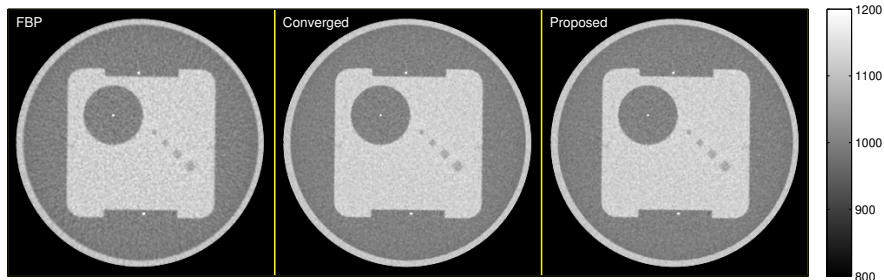


Figure: GEPP: the initial FBP image (left), the reference reconstruction (middle), and the reconstructed image using OS-LALM after 30 iterations (right).

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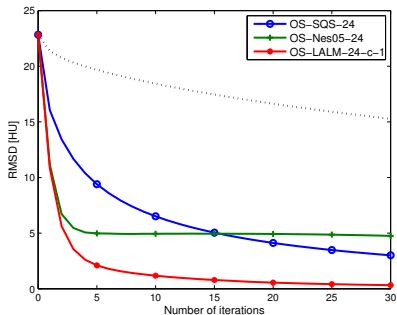
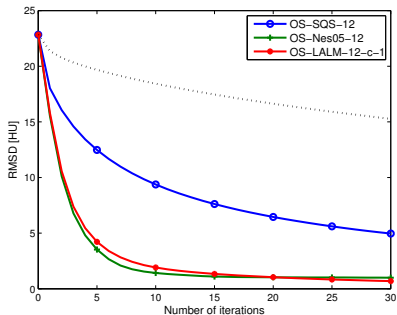


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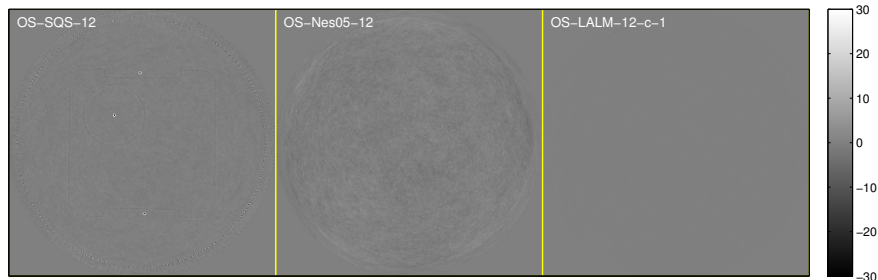


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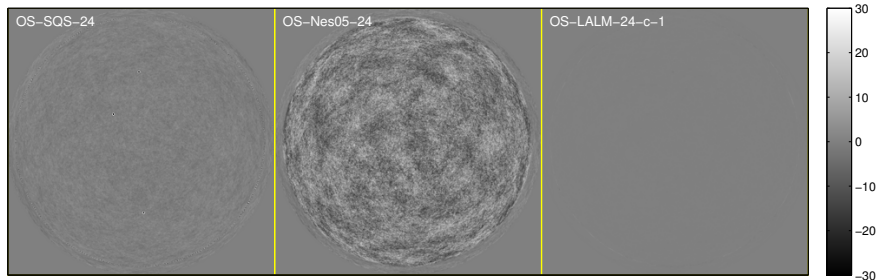


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Chest region half scan

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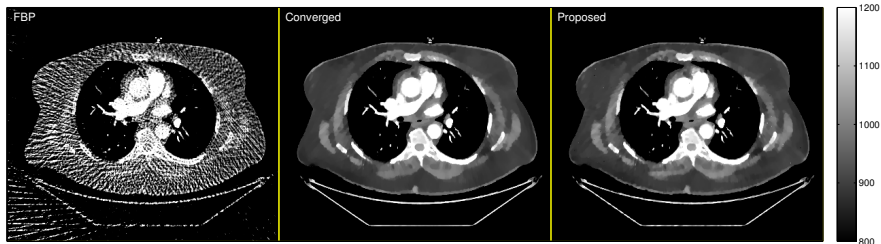


Figure: Chest: the initial FBP image (left), the reference reconstruction (middle), and the reconstructed image using OS-LALM after 100 iterations (right).

Chest region half scan

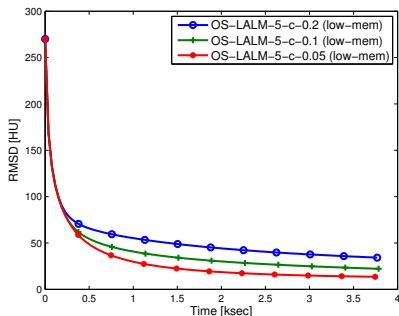
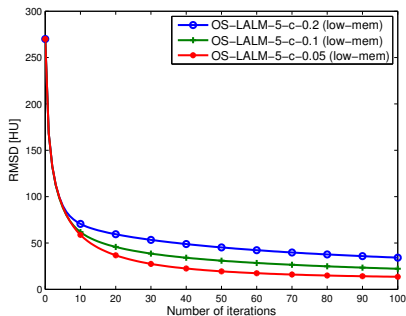


Figure: Chest: RMS differences as a function of iteration (left) and time (right) using OS-LALM with $M = 5$ and different values of η .

Chest region half scan

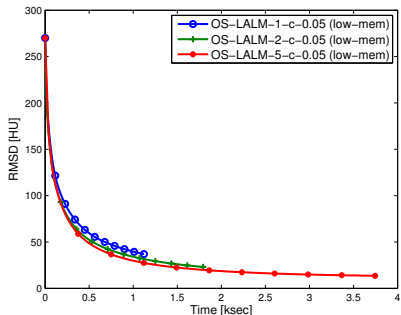
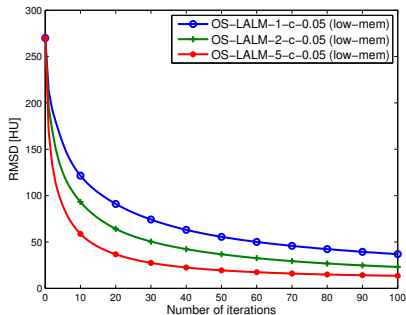


Figure: Chest: RMS differences as a function of iteration (left) and time (right) using OS-LALM with different values of M and $\eta = 0.05$.

Chest region half scan

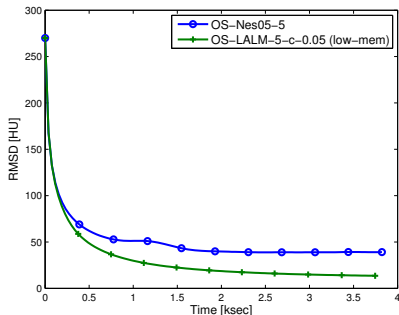
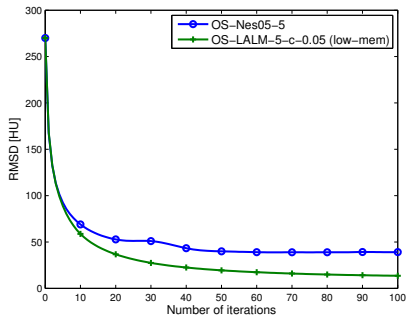


Figure: Chest: RMS differences as a function of iteration (left) and time (right) using different OS-based algorithms with $M = 5$.

Chest region half scan

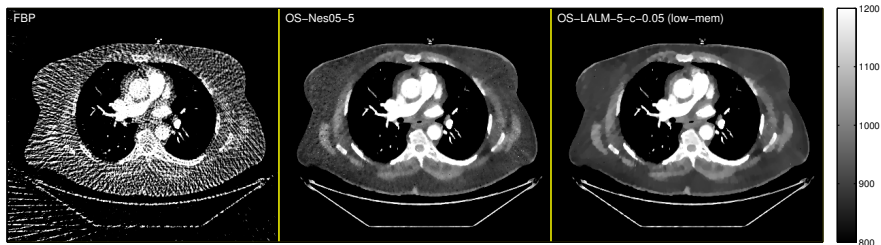


Figure: Chest: reconstructed images using different OS-based algorithms with $M = 5$ after 100 iterations.

Outline

- 1 Background
 - Model-based CT reconstruction
 - Fast (2D) CT reconstruction using ADMM
- 2 OS-LALM: a splitting-based OS algorithm for PWLS problems
 - Linearized AL method with OS acceleration
 - Deterministic downward continuation approach
 - Low-memory OS-LALM with additional variable splits
- 3 Experimental results
 - Low-dose CT with edge-preserving regularizers
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We proposed ...

- A splitting-based OS algorithm, OS-LALM, for solving PWLS X-ray CT image reconstruction problems
- A deterministic downward continuation approach for accelerating the proposed algorithm
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We proposed ...

- A splitting-based OS algorithm, OS-LALM, for solving PWLS X-ray CT image reconstruction problems
- A deterministic downward continuation approach for accelerating the proposed algorithm
- A low-memory variant of the proposed algorithm when considering additional variable splits

Experimental results showed that ...

- The proposed algorithm significantly accelerates the convergence of X-ray CT image reconstruction with negligible overhead
- The proposed algorithm is stable when using many subsets for OS acceleration

Future work

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Theory

- Convergence analysis of OS-LALM when $M > 1$
- Convergence analysis of OS-LALM with downward continuation
- Optimal downward continuation and restart condition
- Convergence analysis of low-mem OS-LALM
- Parameter selection for low-mem OS-LALM

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Extension

- Non-quadratic data-fitting term
- Low-mem OS-LALM with non-smooth potential functions

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THANK YOU!

any question?

Second-order recursive system analysis

Minimize a quadratic function

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- The diagonalized system $\bar{\mathbf{x}} \triangleq \mathbf{V}'\mathbf{x}$ and $\bar{\mathbf{g}} \triangleq \mathbf{V}'\mathbf{g}$ satisfies a 2nd-order recursive system determined by the characteristic polynomial:

$$(1 + \rho) r^2 - 2(1 - \lambda_i/L + \rho/2) r + (1 - \lambda_i/L)$$

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- For $\lambda_i < L/2$, the critically damped system converges fastest

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System behaviors based on the value of ρ (cont'd)

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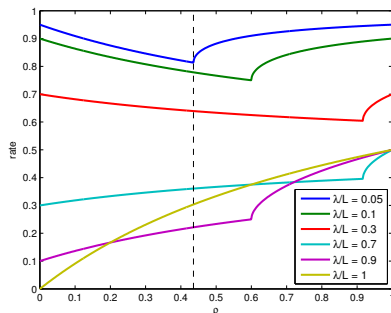


Figure: Asymptotic convergence rate of a system with 6 distinct eigenvalues.

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- If the algorithm is restarted when $\xi(k) > 0$, we shall observe the next restart signal after a further $(\pi/2)\sqrt{L/\mu}$ iterations
- We can easily design a decreasing sequence ρ_k that reaches ρ^* every time we restart the algorithm! [Back](#)