

# 1 Logistics

Next meetings: Wednesday February 27, 9-9:45am and Friday March 1, 12:15 - 1pm

Midterm presentations: Tuesday February 26, 5 - 6:30pm

Expectations for next meetings:

- Problem 7: If I am given a hexagon configuration in terms of the 6 crease vectors, what are the 6 dihedral angles in this configuration?
- Problem 8: mountain / valley labellings
- **[Writing]** Continue writing up relevant discussion from this week in draft of final report
- **[Visualization]** Share code for updated visualization program

## 2 Hexagon configuration space

### 2.1 Changing coordinates

In the hexagon configuration space, we discussed two choices for how to put “coordinates” on this space: crease vectors and dihedral fold angles. How do we change coordinates between these, from crease vectors to dihedral angles?

For example, if we have consecutive crease vectors

$$v_1 = (1, 0, 0), v_2 = (0, 1, 0), v_3 = (-1, 0, 0)$$

then the corresponding dihedral angle is  $\theta_2 = 0$ . If we have consecutive crease vectors

$$v_2 = (0, 1, 0), v_3 = (-1, 0, 0), v_4 = (0, 0, 1)$$

then the corresponding dihedral angle is  $\theta_3 = \frac{\pi}{2}$ .

**Problem 7.** Given three nonzero vectors  $v_0, v_1, v_2 \in \mathbb{R}^3$ , what is a formula to express the dihedral angle between the planes  $p_{01} = \mathbb{R}v_0 + \mathbb{R}v_1$  and  $p_{12} = \mathbb{R}v_1 + \mathbb{R}v_2$ ?

(Possible hint: [https://en.wikipedia.org/wiki/Dihedral\\_angle#Mathematical\\_background](https://en.wikipedia.org/wiki/Dihedral_angle#Mathematical_background))

Our goal will be to use this expression for the angles to express the *energy*

$$E(\Phi) = \left( \sum_i |\theta_i - \pi|^2 \right)^{1/2}$$

of a given fold configuration in terms of the crease vectors, and to study configurations of constant energy.

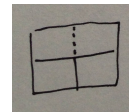
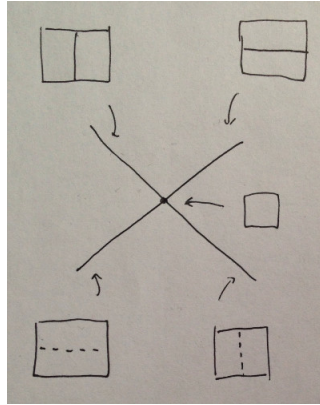
### 2.2 Mountain / valley diagrams

To understand a topological space it often helps to cut it up into smaller, more manageable pieces.

For a fold configuration which is “near flat,” we say a crease is a *mountain fold* if it is higher than a secant line between its two adjacent flat regions, and a *valley fold* if it is lower. (We take the nearby flat configuration as reference for what “higher” and “lower” mean.)

Suppose we label each crease in a configuration with “mountain” or “valley” or neither. Visually we can indicate these respectively by a solid line, a dotted line, or no line.

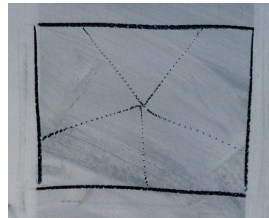
**Example 1.** For two perpendicular creases (so there are 4 total crease vectors), the following shows possible mountain/valley labellings:



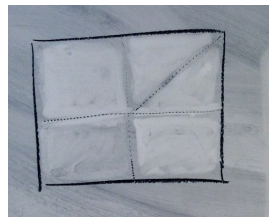
The following mountain/valley labelling is not possible:

**Problem 8.** In the following diagrams with 5 creases coming from a central vertex, which mountain/valley labellings are possible? How do these fit together in configuration space near the unfolded state?

1. creases with equal spacings



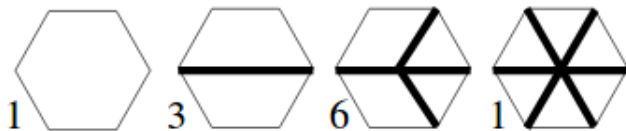
2. creases perpendicular plus one at 45° angle



### 2.3 Neighborhoods of flat configurations

The paper "Hodge Theory and the Art of Paper Folding" claims that for every point in the configuration space that does not lie completely in a plane (i.e. corresponds to a non-degenerate linkage), a small neighborhood around this point looks like an open ball in  $\mathbb{R}^3$ .

The 11 flat configurations of a folded hexagon are discussed in the "Discrete Folding" paper, and shown in Figure 9:



**Problem 5.** [see “Hodge Theory” paper] For each of the 11 flat configurations of the hexagon,

- What are the parameters  $f$ ,  $b$ , and  $w$  as used in Theorem 1.1?
- What is the signature of the null cone describing this neighborhood of configuration space?

Discussion: For the unfolded configuration, we have  $f = 6$ ,  $b = 0$ , and  $w = 1$  (OR  $f = 0$ ,  $b = 6$ ,  $w = -1$ .) The corresponding null cone has signature  $(3, 1)$ . A small neighborhood in configuration space is a cone over two disjoint 2-spheres  $S^2 \times S^0$ .

For the other 10 configurations,  $f = 3$ ,  $b = 3$  and  $w = 0$ . The corresponding null cone has signature  $(2, 2)$ . A small neighborhood in configuration space is a cone over the 2-torus  $S^1 \times S^1$ .

### 3 Quadratic forms

Given an  $n \times n$  (real) symmetric matrix  $Q$  we can define a *quadratic form* on  $\mathbb{R}^n$  by

$$(u, v) \mapsto u^T Q v.$$

We denote this map  $f_Q : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$ . The *null cone* of a quadratic form is the set

$$Z(Q) = \{x \in \mathbb{R}^n \text{ such that } f_Q(x, x) = x^T Q x = 0\}.$$

The *unit null cone* (nonstandard terminology) is the set

$$\hat{Z}(Q) = \{x \in \mathbb{R}^n : x^T Q x = 0 \text{ and } |x|^2 = 1\}.$$

**Problem 6.** For each case below, the null cone  $Z(Q)$  is the cone over the “unit null cone”  $\hat{Z}(Q)$ ; we want a nice geometric description of  $\hat{Z}(Q)$ .

- Describe the null cone of a quadratic form with signature  $(1, 3)$ .
- Describe the null cone of a quadratic form with signature  $(2, 2)$ .
- [Challenge(?)] Describe the null cone of a general quadratic form with signature  $(p, q)$ .

Discussion (b) When the signature is  $(2, 2)$ , the unit null cone is described by

$$\hat{Z}(Q) = \{(a, b, c, d) : a^2 + b^2 - c^2 - d^2 = 0, a^2 + b^2 + c^2 + d^2 = 1\}.$$

By adding and subtracting the two constraints, this is equivalent to

$$\hat{Z}(Q) = \{(a, b, c, d) : a^2 + b^2 = \frac{1}{2}, c^2 + d^2 = \frac{1}{2}\}.$$

This shows that  $\hat{Z}(Q)$  is a *product* of the spaces

$$\{(a, b) : a^2 + b^2 = \frac{1}{2}\} \times \{(c, d) : c^2 + d^2 = \frac{1}{2}\}.$$

Each of these factors is a circle of radius  $\sqrt{1/2}$ , so topologically  $\hat{Z}(Q) \cong S^1 \times S^1$ .

(c) In general, when the signature is  $(p, q)$  the null cone

$$\hat{Z}(Q) = \{a_1^2 + \cdots + a_p^2 - b_1^2 - \cdots - b_q^2 = 0, a_1^2 + \cdots + b_q^2 = 1\}$$

can be expressed equivalently as

$$\{a_1^2 + \cdots + a_p^2 = \frac{1}{2}, b_1^2 + \cdots + b_q^2 = \frac{1}{2}\}$$

so  $\hat{Z}(Q) \cong S^p \times S^q$  is topologically a product of two spheres.

**Example 2.** The null cone of a quadratic form of signature  $(1, 1)$  is two lines passing through the origin. The unit null cone  $\hat{Z}(Q)$  is a set of 4 discrete points, which is equal to the product of spheres  $S^0 \times S^0$ .

**Example 3.** The null cone of a quadratic form of signature  $(2, 1)$  is a “doubled cone”. The unit null cone  $\hat{Z}(Q)$  is two disjoint circles, which is  $S^1 \times S^0$ .