



Information Elicitation Mechanisms for Statistical Estimation



Yuqing Kong, Peking University

Grant Schoenebeck, Biaoshuai Tao, Fang-Yi Yu, University of Michigan

Motivation Question

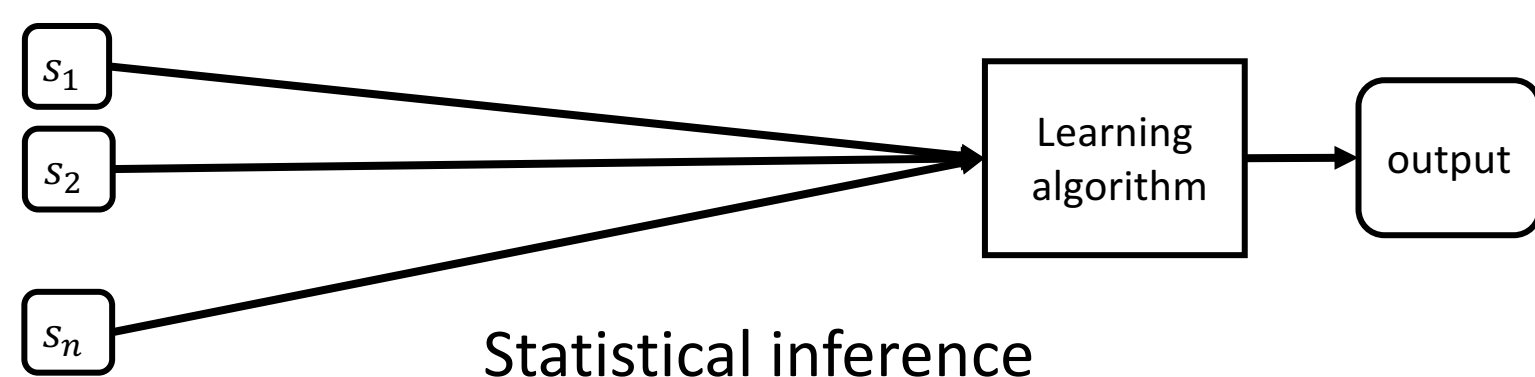
How can we do statistical estimation via crowdsourcing if workers are

- **Selfish** and want to maximize their revenue
- **Bayesian** with complicated signal structure

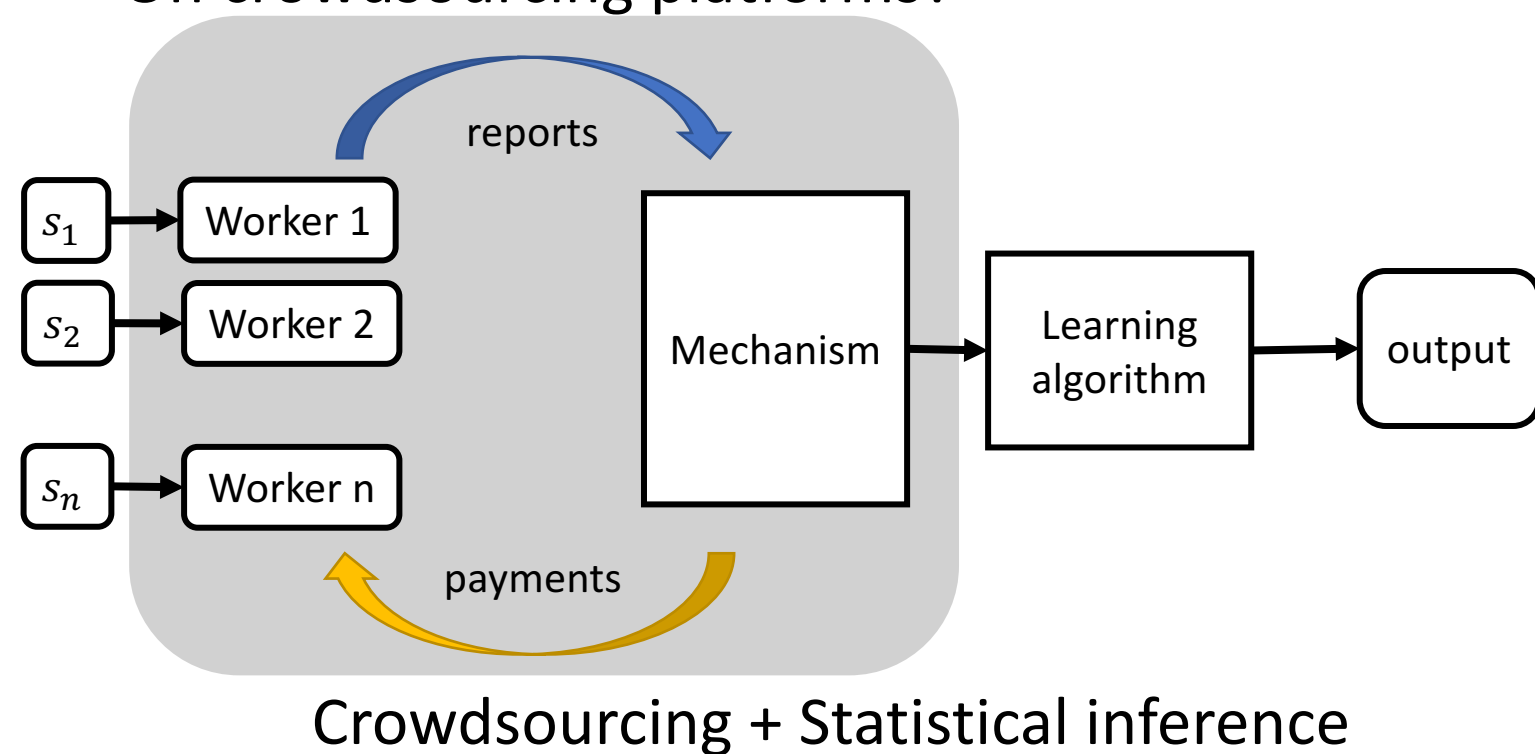
Statistical inference and Crowdsourcing

There is a device that can estimate gravitational acceleration with a small random errors.

- How can we estimate the gravitational acceleration μ at NYC if we have time and the device at hand?



- On crowdsourcing platforms?



Signal Structure

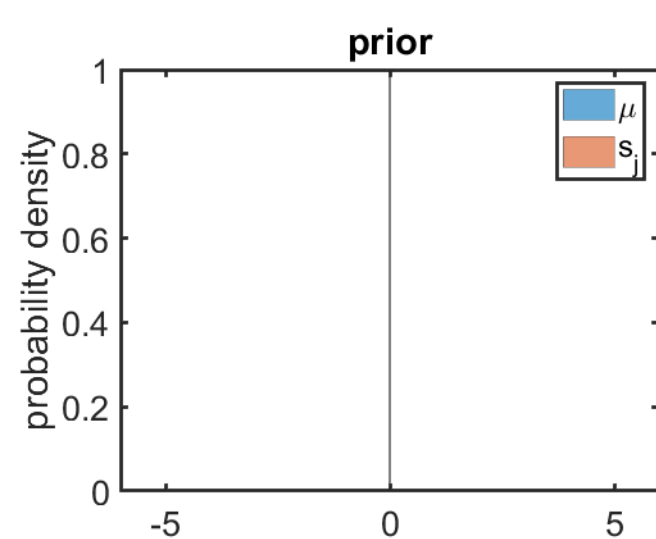
Two-step Gaussian distribution $(n, m_0, \sigma^2, \tau^2)$

- Prior mean $m_0 \in \mathbb{R}^d$ where $d = 1$.
- Covariance matrices $\sigma^2, \tau^2 \in \mathbb{R}^{d \times d}$

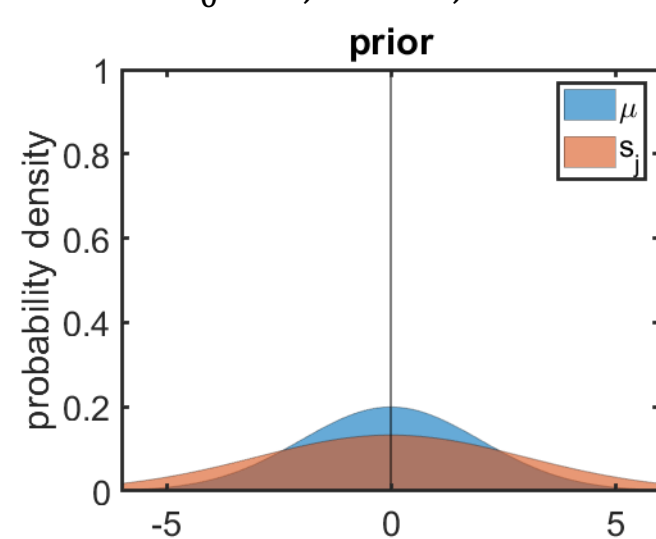
Ground truth $\mu \sim \mathcal{N}(m_0, \sigma^2)$

Agent i 's private signal $s_i \sim \mathcal{N}(\mu, \tau^2)$ i.i.d. with $i \in [n]$

$$m_0 = 0, \sigma^2 = \infty, \tau^2 = 1$$

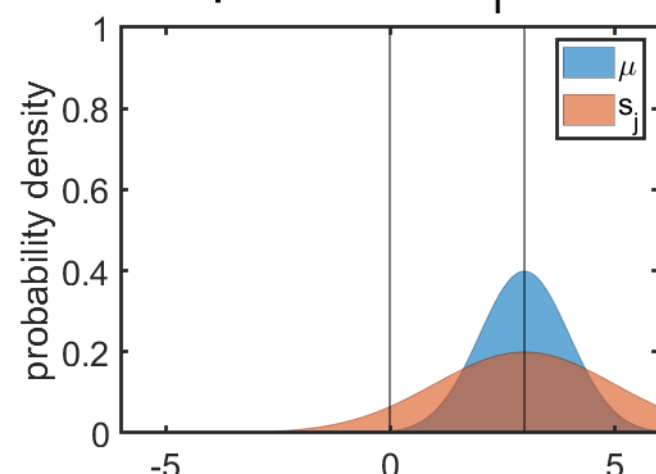


$$m_0 = 0, \sigma^2 = 2, \tau^2 = 1$$

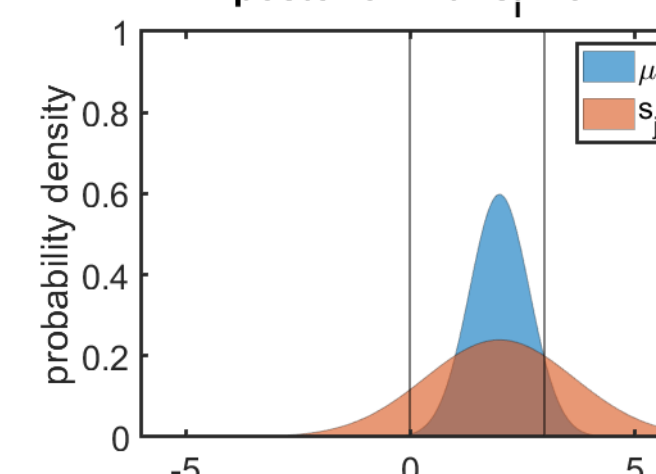


$$\mathbb{E}[s_j | s_i] = \frac{\tau^2 m_0 + \sigma^2 s_i}{\tau^2 + \sigma^2}$$

posterior with $s_i = 3$



posterior with $s_i = 3$



Metric mechanism on Jeffery prior

1. Agents report (\hat{s}_i) after observing signals (s_i)
2. For agent i
 1. Target: a random agent j
 2. Competitor: a random agent k
3. Pay agent i

$$1[\|\hat{s}_j - \hat{s}_k\| > \|\hat{s}_j - \hat{s}_i\|].$$

Theorem (metric mechanism) If $\sigma = \infty$ and $n \geq 4$, the metric mechanism is informed-truthful

- Truth-telling strategy profile $(\hat{s}_i = s_i)$
 - a Bayesian Nash equilibrium and
 - the highest social welfare
- Oblivious strategy profile
 - a strictly smaller social welfare

General Two-step Gaussian

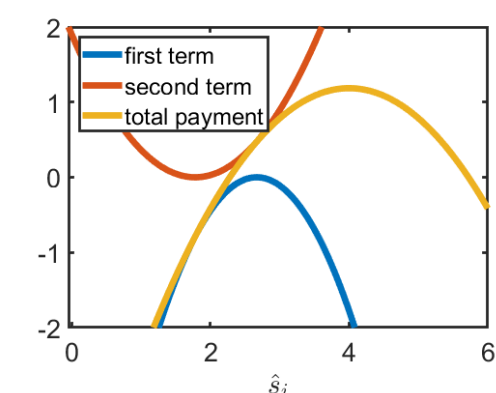
1. Each agent reports a signal and a prediction of the posterior mean (\hat{s}_i, \hat{t}_i) .
2. For agent i ,
 1. Target: a random agent j
 2. Competitor: all other agents
3. Compute L, M and average signal \hat{t}_{-i}
4. Prediction score

$$-L(\hat{s}_j - \hat{t}_i)^2 + M(\hat{s}_j - \hat{t}_{-i})^2$$

5. Information score

$$-M(\hat{s}_i - \hat{t}_{-i})^2 + L(\hat{s}_i - \hat{t}_j)^2$$

Theorem (proxy BTS) If $n \rightarrow \infty$, the proxy BTS mechanism is informed-truthful



1. Each agent reports (\hat{s}_i, \hat{t}_i)
2. For agent $i \in G_0$, pick a target j randomly
3. Compute T
4. Prediction score

$$-(\hat{s}_j - \hat{t}_i)^2$$

5. Information score

$$-\|(T\hat{s}_i - \hat{t}_i) - (T\hat{s}_j - \hat{t}_j)\|$$

Theorem (disagreement mechanism) If $n \geq 3d + 3$, the disagreement mechanism is informed-truthful

Discussion and Conclusion

- Streamline agents' report requirement: signal, posterior mean, or posterior belief
- Go beyond finite and simple signal structure: exponential family, graphical model, ...
- Elicit information through geometry of parameter space